

Let  $J = [a, b] \subseteq \mathbb{R}$  be an interval and  $0 < q < 1$ ,  $q$ -derivative of a continuous function  $f : J \rightarrow \mathbb{R}$  at a point  $x \in J$  is given in the following definition.

**Definition 1.** (Sudsutad et al., 2015) Let  $f : J \rightarrow \mathbb{R}$  be a continuous function and let  $x \in J$ . Then  $q$ -derivative of  $f$  at  $x$  is defined by the expression

$$(0.1) \quad {}_a D_q f(x) = \frac{f(x) - f(qx + (1-q)a)}{(1-q)(x-a)}, x \neq a.$$

Since  $f : J \rightarrow \mathbb{R}$  is a continuous function, thus we have  ${}_a D_q f(a) = \lim_{x \rightarrow a} {}_a D_q f(x)$ . The function  $f$  is said to be  $q$ -differentiable on  $J$  if  ${}_a D_q f(x)$  exists for all  $x \in J$ . If  $a = 0$  in (0.1), then  ${}_0 D_q f(x) = D_q f(x)$ , where  $D_q f(x)$  is the well-known  $q$ -derivative of  $f$  defined by the expression

$$(0.2) \quad D_q f(x) = \frac{f(qx) - f(x)}{(1-q)x}, x \neq 0.$$

For more details on  $q$ -derivative given above by (0.2), we refer the reader to (Kac and Cheung, 2002).

**Definition 2.** (Sudsutad et al., 2015) Let  $f : J \rightarrow \mathbb{R}$  be a continuous function. A second-order  $q$ -derivative on  $J$  denoted by  ${}_a D_q^2 f$ , provided  ${}_a D_q f$  is  $q$ -differentiable on  $J$ , is defined as  ${}_a D_q^2 f = {}_a D_q ({}_a D_q f) : J \rightarrow \mathbb{R}$ . Similarly higher order  $q$ -derivatives on  $J$  is defined by  ${}_a D_q^n f = {}_a D_q ({}_a D_q^{n-1} f) : J \rightarrow \mathbb{R}$ .

The following result is very important to evaluate  $q$ -derivative of monomials.

**Lemma 1.** (Sudsutad et al., 2015) Let  $\alpha \in \mathbb{R}$  and  $0 < q < 1$ , we have

$${}_a D_q (x-a)^\alpha = \left( \frac{1-q^\alpha}{1-q} \right) (x-a)^{\alpha-1}.$$

One can find further properties of  $q$ -derivatives in (Tariboon and Ntouyas, 2013).

**Definition 3.** (Sudsutad et al., 2015) Suppose that  $f : J \rightarrow \mathbb{R}$  is a continuous function. Then the definite  $q$ -integral on  $J$  is defined by

$$(0.3) \quad \int_a^x f(x) {}_a d_q x = (x-a)(1-q) \sum_{n=0}^{\infty} q^n f(q^n x + (1-q^n)a)$$

for  $x \in J$ . If  $c \in (a, x)$ , then the definite  $q$ -integral on  $J$  is defined as

$$\begin{aligned} \int_c^x f(x) {}_a d_q x &= \int_a^x f(x) {}_a d_q x - \int_a^c f(x) {}_a d_q x \\ &= (x-a)(1-q) \sum_{n=0}^{\infty} q^n f(q^n x + (1-q^n)a) \\ &\quad - (c-a)(1-q) \sum_{n=0}^{\infty} q^n f(q^n c + (1-q^n)a). \end{aligned}$$

If  $a = 0$  in (0.3), then we get the classical  $q$ -definite integral defined by see (Ernst, 2012).

$$\int_0^x f(x) {}_0 d_q x = (1-q)x \sum_{n=0}^{\infty} q^n f(q^n x), x \in [0, \infty).$$

The following results hold about definite  $q$ -integrals.

**Theorem 1.** (Tariboon and Ntouyas, 2013) Let  $f : J \rightarrow \mathbb{R}$  be a continuous function. Then

- (1)  ${}_a D_q \int_a^x f(t)_a d_q t = f(x)$
- (2)  $\int_c^x {}_a D_q f(t)_a d_q t = f(x) - f(c)$ ,  $c \in (a, x)$ .

**Theorem 2.** (Tariboon and Ntouyas, 2013) Suppose that  $f, g : J \rightarrow \mathbb{R}$  are continuous functions,  $\alpha \in \mathbb{R}$ . Then, for  $x \in J$ ,

- (1)  $\int_a^x [f(t) + g(t)]_a d_q t = \int_a^x f(t)_a d_q t + \int_a^x g(t)_a d_q t$ ;
- (2)  $\int_a^x \alpha f(t)_a d_q t = \alpha \int_a^x f(t)_a d_q t$ ;
- (3)  $\int_c^x f(t)_a D_q g(t)_a d_q t = f(t)g(t)|_c^x - \int_c^x g(qt + (1-q)a)_a D_q f(t)_a d_q t$ ,  $c \in (a, x)$ .

The following is a valuable result to evaluate definite  $q$ -integrals of monomials.

**Lemma 2.** (Sudsutad et al., 2015) For  $\alpha \in \mathbb{R} \setminus \{-1\}$  and  $0 < q < 1$ , the following formula holds:

$$\int_a^x (x-a)^\alpha {}_a d_q x = \left( \frac{1-q}{1-q^{\alpha+1}} \right) (x-a)^{\alpha+1}.$$

We recall the following definitions before proving our main results.

**Definition 4.** (Dragomir, 2001) A mapping  $f : [a, b] \times [c, d] \rightarrow \mathbb{R}$  is said to be convex on  $[a, b] \times [c, d]$  if the inequality

$$f(\lambda x + (1-\lambda)z, \lambda y + (1-\lambda)w) \leq \lambda f(x, y) + (1-\lambda)f(z, w)$$

holds for all  $(x, y), (z, w) \in [a, b] \times [c, d]$  and  $\lambda \in [0, 1]$ .

**Definition 5.** (Dragomir, 2001) A function  $f : [a, b] \times [c, d] \rightarrow \mathbb{R}$  is said to be convex on co-ordinates on  $[a, b] \times [c, d]$  if the partial mappings  $f_y : [a, b] \rightarrow \mathbb{R}$ ,  $f_y(u) = f(u, y)$  and  $f_x : [c, d] \rightarrow \mathbb{R}$ ,  $f_x(v) = f(x, v)$  are convex where defined for all  $x \in [a, b], y \in [c, d]$ .

A different approach of stating convexity of  $f$  on co-ordinates on  $[a, b] \times [c, d]$  is given in the definition below.

**Definition 6.** (Latif and Alomari, 2009) A function  $f : [a, b] \times [c, d] \rightarrow \mathbb{R}$  is said to be convex on co-ordinates on  $[a, b] \times [c, d]$  if the inequality

$$\begin{aligned} & f(tx + (1-t)y, sz + (1-s)w) \\ & \leq tsf(x, z) + t(1-s)f(x, w) + s(1-t)f(y, z) + (1-t)(1-s)f(y, w) \end{aligned}$$

holds for all  $(t, s) \in [0, 1] \times [0, 1]$  and  $(x, z), (y, w) \in [a, b] \times [c, d]$ .

**Definition 7.** (Özdemir et al., 2012) A function  $f : [a, b] \times [c, d] \subset \mathbb{R}^2 \rightarrow \mathbb{R}$  is said to be quasi-convex on  $[a, b] \times [c, d]$  if the inequality

$$f(\lambda x + (1-\lambda)z, \lambda y + (1-\lambda)w) \leq \max\{f(x, y), f(z, w)\}$$

holds for all  $(x, y), (z, w) \in [a, b] \times [c, d]$  and  $\lambda \in [0, 1]$ .

**Definition 8.** (Özdemir et al., 2012) A function  $f : [a, b] \times [c, d] \rightarrow \mathbb{R}$  is said to be quasi-convex on the co-ordinates on  $[a, b] \times [c, d]$  if the partial mappings  $f_y : [a, b] \rightarrow \mathbb{R}$ ,  $f_y(u) = f(u, y)$  and  $f_x : [c, d] \rightarrow \mathbb{R}$ ,  $f_x(v) = f(x, v)$  are quasi-convex where defined for all  $x \in [a, b], y \in [c, d]$ .

Another way of expressing the concept of co-ordinated quasi-convex functions is stated in the definition below.

**Definition 9.** (*Özdemir et al., 2012*) A function  $f : [a, b] \times [c, d] \subset \mathbb{R}^2 \rightarrow \mathbb{R}$  is said to be quasi-convex on co-ordinates on  $[a, b] \times [c, d]$  if

$$f(tx + (1-t)z, sy + (1-s)w) \leq \max \{f(x, y), f(x, w), f(z, y), f(z, w)\}$$

holds for all  $(x, y), (z, w) \in [a, b] \times [c, d]$  and  $(s, t) \in [0, 1] \times [0, 1]$ .