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Original article

# Computable generalization of fractional kinetic equation with special functions

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## ABSTRACT

The primarily object of this article is to derive the solutions of modified fractional kinetic equations (MFKEs) containing the incomplete Aleph functions by using the application of Elzaki and inverse Elzaki transforms and hereto we also established some novel results such as the Elzaki transform of well-known the Riemann–Liouville operator and the incomplete Aleph functions (IAFs). The solutions of modified FKEs discusses in this article can be utilized to figures out the variation of the chemical composition in our solar system. In this article, we also see that the character of thermonuclear function is presented in terms of the incomplete  $\aleph$ -functions and many more special functions through some interesting corollaries. Finally, we established here a compact and easily figure out solutions in form of incomplete special functions and display the graphs of the obtained results in the end of this article to show the behavior of integral operator of fractional order on reaction rate of the particle. Furthermore, results holds here are also associated to the recent investigation of feasible astrophysical solutions of solar system problems. The derived results notify the known results more precisely.

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## 1. Introduction

Stars have attracted scientists and astronomers equally. Some amazing things whether it is our sun-like stars or solar system akin to our other galaxies. A star is creating when a bit of gas is destroyed onto its own gravity. When mass and length of interstellar cloud extend to certain limits, then the clouds diverge from entity in hydrostatic equilibrium (HE) and are destroyed. If its gravitational force is equal is equal to its internal pressure then in this situation the system is said to be hydrostatic equilibrium. Therefore the system is neither burst nor collapse. Nevertheless in the formation of a star the gravitational force inside the cloud should be more than its internal pressure. As the interstellar cloud

collapse inward due to the variation of force inside, the temperature jump up when the cloud temperature reaches  $10^4\text{k}$ , then nuclear fusion will begin. Because of nuclear fusion the cloud radiate the light and protostar come in existence. In this phase stellar is known as pre-main sequence.

In thermal and HE, a star can be considered as a uniform gas sphere with insignificant spinning and magnetic field. The internal structure of star is entirely gases and it is characterized by three parameters; temperature, pressure & mass. Mathematical models (MMs) and structures of stars are examined and it is depend upon the above parameters as well as its based on equation of state, transluence and rate of nuclear energy produce. The hypothesis of thermal and HE show that there is no dependency on time in the MMs as well as in the equations expressing the inside formation of the star (Kourganoff, 1973; Perdang, 1976; Clayton, 1983). The assessment of the star is conducted by a system of differential equation. A system of differential equation is used in assessment of the star like sun, kinetic equation (KE) is an equation that is appear in non-equilibrium statistical physics (Lebowitz and Montroll, 1984). The result obtained from kinetic-equation estimate the distribution function of the movable position of a solitary particle, which is normally based on time & velocity. Thus, we can say that

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KEs characterize the rate of change of chemical composition of star for every kind in the form of reaction rate for production & destruction of that kind (Kourganoff, 1973; Perdang, 1976; Clayton, 1983).

Let us assume a random reaction identify by a time dependent quantity  $M = M(x)$ . Then we estimate the  $\frac{dM}{dx}$  by the following equation

$$\frac{dM}{dx} = -\delta + p, \tag{1}$$

where  $\delta$  is destruction rate and  $p$  is the production rate of  $M$ . In general  $\delta = \delta(M)$  or  $p = p(M)$ . Then the functional –differential equation expressing the reaction rate for destruction & production carried out by Haubold and Mathai (2000):

$$\frac{dM}{dx} = -\delta(M_x) + p(M_x), \tag{2}$$

where  $M_x$  refer the function presented as

$$M_x(x^*) = M(x - x^*), x^* > 0.$$

Haubold and Mathai (2000) considered a particular case of (2), when the quantity  $M(x)$  are ignored, then the Eq. (2) become

$$\frac{dM_i}{dx} = -c_i M_i(x), \tag{3}$$

where  $c_i > 0$  (destruction of species  $i$ ) and  $c_i < 0$ (production of species  $i$ ) subject to the condition  $M_i(x = 0) = M_0$  is the number density of species  $i$  at time  $x = 0$  and Eq. (3) is known as standard kinetic equation (SKE). Then the Eq. (3), after solution can be written as

$$M_i(x) = M_0 e^{-c_i x}, \tag{4}$$

if we drop index  $i$  due to sake of brevity in Eq. (3), then Haubold and Mathai (2000), after integration demonstrate the SKE (3) as

$$M(x) - M_0 = -c_0 D_x^{-1} M(x), \tag{5}$$

here  ${}_0D_x^{-1}$  denote the standard R-L operator. After this the operator mention in Eq. (5), is generalized into arbitrary order operator and it is defined as

$$M(x) - M_0 = -c^\omega {}_0D_x^{-\omega} M(x), \tag{6}$$

where  ${}_0D_x^{-\omega}$  is the familiar R-L integral operator (Oldham and Spanier, 1974; Miller and Ross, 1993).

finally, the solution of SKE (6) obtained in series form Haubold and Mathai (2000) as

$$M(x) = M_0 \sum_{h=0}^{\infty} \frac{(-1)^h}{\Gamma(\omega h + 1)} (cx)^{\omega h}. \tag{7}$$

So far, a lot of research has been done in last three decades to improve the reaction rate of particle via FKE. A number of methods are used for solving the generalized FKE (GFKE) and it is solved earlier by several authors such as Saichev and Zaslavsky (1997), investigated the potential generalization of the normal diffusion equation by using FKE as well as they established the relation between FKE and Montroll-Weiss equation and generalized the Kolmogorov-Feller equation. In a series of research papers so far, many authors have investigated FKE and derived the solution in easy and compact form to figure out the particle reaction rate such as Haubold and Mathai (2000), developed the solution of KE to calculate the variation of chemical composition of stars and discuss the contribution of thermonuclear function in terms of G & H functions. After this Saxena et al. (2002), investigated the FKE and derived the generalized FKE in-terms of the Mittag-Leffler (M-L) function, which was an increment of what had been done by Haubold and Mathai (2000), in other article, Saxena et al. (2004a), established the solutions of three GFKE in form of generalized M-L functions. Further, Saxena et al. (2004b), explored the

solution of integrated form of FKE and presented the solution in the form of the Wright function. In 2008, Saxena and Kalla (2008), introduced a new way to solve the FKEs which was in addition to the Laplace transform technique. At the same time Chaurasia and Pandey (2008), developed a compact and effortless computable solution of GFKE and presented it in the form of the Lorenzo-Hartely function which is very helpful to compute the reaction rate. In continuation of solution of GFKE, Chaurasia and Kumar (2010), established the solution of GFKE in associated with M-series and derived some particular cases in form of well-known GMLF. Recently Chaurasia and Singh (2015), further derived the solution of GFKE involving GMLF and the Rathie I-function. Very recently, Bansal et al. (2020b), introduced a new concept of the incomplete I- function and derived the solution of FKE involving the incomplete I-function (IIF). For the last few decades, we are seeing that a lot of researcher has solved GFKE and has contributed greatly to modify the particle reaction rate for more detail sees (Chaurasia and Singh, 2011; Nisar et al., 2016; Nisar and Qi, 2017). The potential uses of FKEs in several problems come to the light in some astrophysical problems, Science and engineering can be referring these monographs (Podlubny, 1999; Hilfer, 2000; Kilbas et al., 2006). In the present article the results are achieved in a compact form in terms of the incomplete  $\aleph$ -functions (Bansal et al., 2020c), by using the application of Elzaki and inverse Elzaki transform (Elzaki, 2011; Singh et al., 2019a, 2019b). The article is unified as follows, Section 2 hold the definition of IGFs, incomplete Aleph-functions, Elzaki transform and R-L operator. In Section 3, we investigate the Elzaki transform of R-L operator and the incomplete Aleph-functions. After that in Section 4, we established the solution of MFKE while some special cases, are also discussed in Section 5 through corollaries in terms of the incomplete –I functions (IIFs),  $\aleph$ -function, H-function. The results established in this article come up with an addition of consequences that are given in recent paper Bansal et al. (2020b). Finally, we plot the graph of the obtained results and found that the reaction rate decreases with enhancement of time and continuously depends on the value of fractional parameter.

In view of great significance and widely used of KE in diverse physical problems, especially in astrophysics. So that we further, derived the solution of MFKE associated with the incomplete  $\aleph$ -functions.

In the history of mathematics, the incomplete gamma functions (IGFs) are kinds of special-functions that appear as solutions of diverse problems of mathematical for instance some specific integrals are extensively used in several area of mathematics in addition to other areas such as probability theory, Kinematics (specially come to know time, displacement & velocity), thermodynamics (to look into the change in free energy b/w two states). The IGFs has a very old history of research (see e.g. Prym, 1877; Abramowitz and Stegun, 1984; Arfken, 1985; Chaudhry and Zubair, 1995). After that researcher has been done a lots of work and take a step to proceed the research and development of well-known IGFs  $\gamma(\vartheta, t)$  and  $\Gamma(\vartheta, t)$  defined in (8) & (9).The IGFs are very crucial part of special function in view of their widely used and great importance in statistics, Physics, engineering and many more area of mathematics as mention above.

Recentaly, Srivastava et al. (2012), explore a well-known the incomplete pochhammer symbols and discuss their utility and fundamental properties to the incomplete Gauss hypergeometric (IGH) function and other associated functions which are probably very helpful in definite and semi-definite integrals of several special functions and can be implement these function in communication theory, probability theory and ground water pumping modeling (GWPM). The important aspect of the gamma function is that it decompose into IGFs and seems to be a closed form solution to a significant number of problems arise in plasma wave,

science, engineering, astrophysics, mathematics and statistics as well as in configuration of particle acceleration can be demonstrate in terms of the IGFs given by (8) & (9). Taking inspiring from his current research work [Srivastava et al. \(2012\)](#), explore a well-established incomplete H-function  $\gamma_{p,Q}^{M,N}(z)$  and  $\Gamma_{p,Q}^{M,N}(z)$  along with develop some special cases like Incomplete Fox-Wright generalized hypergeometric functions and established many fascinating basic properties such as decomposition, several Integral transforms, derivative formulas and many more ([Srivastava et al., 2018](#)). Recently, [Srivastava et al. \(2012, 2018\)](#), investigated the incomplete Pochhammer symbols, incomplete H-functions and incomplete  $\bar{H}$  – functions. Enthusiastic by the novel research work of incomplete special functions which is done by some author's mention earlier, [Bansal and Kumar \(2020\)](#); [Bansal et al. \(2020c\)](#), investigated the IIFs and the IAFs. Therefore keeping in mind the greatness and utility of KE in classical astrophysical problems, we further, investigate the compact and computable solution of MFKE involving the incomplete  $\aleph$ -functions.

**2. Definitions and preliminaries**

In this section, we develop a few important fundamental definition associated to fractional calculus, Elzaki transform and special function to understand the further results and lemmas.

**2.1. Incomplete gamma functions  $\gamma(\vartheta, t)$  and  $\Gamma(\vartheta, t)$**

The well-known incomplete gamma functions  $\gamma(\vartheta, t)$  and  $\Gamma(\vartheta, t)$  (also known as [Prym, 1877](#)) functions are expressed in the following manner [Abramowitz and Stegun, 1984](#); [Arfken, 1985](#); [Chaudhry and Zubair, 1995](#)):

$$\gamma(\vartheta, t) = \int_0^t x^{\vartheta-1} e^{-x} dx, (\Re(\vartheta) > 0; t \geq 0), \tag{8}$$

and

$$\Gamma(\vartheta, t) = \int_t^\infty x^{\vartheta-1} e^{-x} dx, (t \geq 0; \Re(\vartheta) > 0 \text{ when } t = 0), \tag{9}$$

respectively, hold the following decomposition formula:

$$\gamma(\vartheta, t) + \Gamma(\vartheta, t) = \Gamma(\vartheta), (\Re(\vartheta) > 0). \tag{10}$$

where  $\Gamma(\vartheta)$  well-known Gamma-function is defined as

$$\Gamma(\vartheta) = \int_0^\infty x^{\vartheta-1} e^{-x} dx, (\Re(\vartheta) > 0). \tag{11}$$

Each of these functions play a vital role in the analysis of an analytic solutions of a numbers of problems in various field of GWP modeling, theory of Probability, quantum physics, Communication theory, Mathematical Physics, Science and engineering (see, for instance, [Kilbas et al., 2006](#); [Prym, 1877](#); [Andrews, 1984](#); [Andrews et al., 1999](#); [Srivastava and Karlsson, 1985](#); [Temme, 1996](#); [Kumar et al., 2019, 2020](#); [Singh et al., 2019a, 2019b](#); [Gill et al., 2019](#); [Baleanu et al., 2020](#); [Bansal et al., 2020a](#); [Modi et al., 2020](#)).

**2.2. Incomplete Aleph functions**

The Incomplete Aleph functions ( $\Gamma_{p_i, q_i, \sigma_i; r}^{m, n}$ ) and ( $\gamma_{p_i, q_i, \sigma_i; r}^{m, n}$ ) consisting the incomplete gamma functions  $\gamma(\vartheta, t)$  and  $\Gamma(\vartheta, t)$  recently, introduced by [Bansal et al. \(2020c\)](#), and defined as:

$$(\Gamma)_{p_i, q_i, \sigma_i; r}^{m, n}(\chi) = (\Gamma)_{p_i, q_i, \sigma_i; r}^{m, n} \left[ \chi \left| \begin{matrix} (\alpha_1, \mathfrak{A}_1), t, & (\alpha_j, \mathfrak{A}_j)_{2, n}, & [\sigma_j(\alpha_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1, m}, & [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right] \tag{12}$$

$$= \frac{1}{2\pi i} \int_{\mathcal{C}} \Phi(\eta, t) x^{-\eta} d\eta,$$

where  $x \neq 0$ , and

$$\Phi(\eta, t) = \frac{\Gamma(1 - \alpha_1 - \mathfrak{A}_1 \eta, t) \prod_{j=1}^m \Gamma(b_j + \mathfrak{B}_j \eta) \prod_{j=2}^n \Gamma(1 - \alpha_j - \mathfrak{A}_j \eta)}{\sum_{i=1}^r \sigma_i \left[ \prod_{j=m+1}^{q_i} \Gamma(1 - b_{ji} - \mathfrak{B}_{ji} \eta) \prod_{j=n+1}^{p_i} \Gamma(\alpha_{ji} + \mathfrak{A}_{ji} \eta) \right]}, \tag{13}$$

and

$$(\gamma)_{p_i, q_i, \sigma_i; r}^{m, n}(\chi) = (\gamma)_{p_i, q_i, \sigma_i; r}^{m, n} \left[ \chi \left| \begin{matrix} (\alpha_1, \mathfrak{A}_1), t, & (\alpha_j, \mathfrak{A}_j)_{2, n}, & [\sigma_j(\alpha_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1, m}, & [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right] \tag{14}$$

$$= \frac{1}{2\pi i} \int_{\mathcal{C}} \Psi(\eta, t) x^{-\eta} d\eta,$$

where  $x \neq 0$ , and

$$\Psi(\eta, t) = \frac{\gamma(1 - \alpha_1 - \mathfrak{A}_1 \eta, t) \prod_{j=1}^m \Gamma(b_j + \mathfrak{B}_j \eta) \prod_{j=2}^n \Gamma(1 - \alpha_j - \mathfrak{A}_j \eta)}{\sum_{i=1}^r \sigma_i \left[ \prod_{j=m+1}^{q_i} \Gamma(1 - b_{ji} - \mathfrak{B}_{ji} \eta) \prod_{j=n+1}^{p_i} \Gamma(\alpha_{ji} + \mathfrak{A}_{ji} \eta) \right]}, \tag{15}$$

for details of existence conditions see [Bansal et al. \(2020c\)](#).

**2.3. Elzaki transform**

Let the function  $h(x)$  belongs to a class  $\aleph$ ,

Where  $\aleph = \{h(x) : \exists N, p_1, p_2 > 0 \text{ such that } |h(x)| < Ne^{x/p_1} \text{ if } x \in (-i)^j \times [0, \infty)\}$ ,

Elzaki transform of function  $h(x)$  introduced by Tarig M. Elzaki is defined as ([Elzaki, 2011](#)):

$$E[h(x)] = u \int_0^\infty e^{-\frac{x}{u}} h(x) dx = L(u), \quad x > 0, \quad u \in (-p_1, p_2). \tag{16}$$

**2.4. Convolution property**

The Elzaki convolution property of  $f(x)$  and  $g(x)$  is given by

$$\mathbb{E}[(f * g)(x)] = \frac{1}{u} \mathfrak{F}(u) \mathfrak{G}(u), \tag{17}$$

where  $\mathfrak{F}(u)$  and  $\mathfrak{G}(u)$  are the Elzaki transform of  $f(x)$  and  $g(x)$  resp., and

$$(f * g)(x) = \int_0^x f(x-u)g(u)du.$$

**2.5. R-L integral operator**

A well-known integral operator introduced by Riemann-Liouville and presented as ([Oldham and Spanier, 1974](#); [Miller and Ross, 1993](#)).

$$[{}_0 D_x^{-\omega} \eta(x)] = \frac{1}{\Gamma(\omega)} \int_0^x \frac{\eta(\tau)}{(x-\tau)^{1-\omega}} d\tau, (R(\omega) > 0). \tag{18}$$

**3. Elazki transform of Riemann-Liouville integral operator & incomplete Aleph functions** ( $\Gamma_{p_i, q_i, \sigma_i; r}^{m, n}$ ) and ( $\gamma_{p_i, q_i, \sigma_i; r}^{m, n}$ )

In this portion, we introduce a formula of the Elzaki transform of R-L integral operator and the incomplete  $\aleph$ -function.

Lemma 3.1. The Elzaki transform of R-L integral operator is given by

$$\mathbb{E}[{}_0D_x^{-\omega} \mathfrak{y}(x)] = u^\omega \mathfrak{y}(u), \quad (\Re(\omega) > 0). \tag{19}$$

Proof. Elzaki transform of the function defined in (18) is given by

$$\begin{aligned} \mathbb{E}[{}_0D_x^{-\omega} \mathfrak{y}(x)] &= \mathbb{E} \left[ \frac{1}{\Gamma(\omega)} \int_0^x \frac{\mathfrak{y}(\tau)}{(x-\tau)^{1-\omega}} d\tau \right], \\ &= \mathbb{E} \left[ \frac{1}{\Gamma(\omega)} \int_0^x (x-\tau)^{\omega-1} \mathfrak{y}(\tau) d\tau \right], \end{aligned}$$

applying the convolution property of the Elzaki transform on above equation, we have

$$= \frac{1}{\Gamma(\omega)} \cdot \frac{1}{u} \mathbb{E}[\mathfrak{y}(x)] \cdot \mathbb{E}[(x)^{\omega-1}],$$

finally, yield the desired result.

Lemma 3.2. The Elzaki transform of the incomplete Aleph functions  $(\Gamma) \aleph_{p_i, q_i, \sigma_i; r}^{m, n}(x)$  and  $(\gamma) \aleph_{p_i, q_i, \sigma_i; r}^{m, n}(x)$  is given by

$$\begin{aligned} &\mathbb{E} \left[ x^{\zeta-1} (\Gamma) \aleph_{p_i, q_i, \sigma_i; r}^{m, n} \left[ h x^\zeta \left| \begin{matrix} (a_1, \mathfrak{A}_1, t), (a_j, \mathfrak{A}_j)_{2,n}, [\sigma_j(a_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1,m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right]; u \right] = \\ &u^{\zeta+1} (\Gamma) \aleph_{p_i+1, q_i, \sigma_i; r}^{m, n+1} \left[ h u^\zeta \left| \begin{matrix} (a_1, \mathfrak{A}_1, t), (1-\zeta, \chi)(a_j, \mathfrak{A}_j)_{2,n}, [\sigma_j(a_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1,m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right], \tag{20} \end{aligned}$$

and

$$\begin{aligned} &\mathbb{E} \left[ x^{\zeta-1} (\gamma) \aleph_{p_i, q_i, \sigma_i; r}^{m, n} \left[ h x^\zeta \left| \begin{matrix} (a_1, \mathfrak{A}_1, t), (a_j, \mathfrak{A}_j)_{2,n}, [\sigma_j(a_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1,m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right]; u \right] = \\ &u^{\zeta+1} (\gamma) \aleph_{p_i+1, q_i, \sigma_i; r}^{m, n+1} \left[ h u^\zeta \left| \begin{matrix} (a_1, \mathfrak{A}_1, t), (1-\zeta, \chi)(a_j, \mathfrak{A}_j)_{2,n}, [\sigma_j(a_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1,m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right], \tag{21} \end{aligned}$$

provided that each member exit in (20) and (21).

Proof. We begin the proof of (20), by taking the Elzaki transform of left hand side in (20), then

$$\begin{aligned} &\mathbb{E} \left[ x^{\zeta-1} (\Gamma) \aleph_{p_i, q_i, \sigma_i; r}^{m, n} \left[ h x^\zeta \left| \begin{matrix} (a_1, \mathfrak{A}_1, t), (a_j, \mathfrak{A}_j)_{2,n}, [\sigma_j(a_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1,m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right]; u \right] \\ &= \mathbb{E} \left[ x^{\zeta-1} \frac{1}{2\pi i} \int_{\mathcal{L}} \Phi(\eta, t) (h x^\zeta)^{-\eta} d\eta; u \right], \end{aligned}$$

where  $\Phi(\eta, t)$  is given by (13).

Changing the order of integration that is acceptable under the prescribed condition of the incomplete Aleph-function, then we have

$$\begin{aligned} &\mathbb{E} \left[ x^{\zeta-1} (\Gamma) \aleph_{p_i, q_i, \sigma_i; r}^{m, n} \left[ h x^\zeta \left| \begin{matrix} (a_1, \mathfrak{A}_1, t), (a_j, \mathfrak{A}_j)_{2,n}, [\sigma_j(a_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1,m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right]; u \right] \\ &= \frac{1}{2\pi i} \int_{\mathcal{L}} \Phi(\eta, t) h^{-\eta} \mathbb{E}[x^{\zeta-\eta-1}] d\eta. \end{aligned}$$

By using result of the Elzaki transform, then

$$\begin{aligned} &\mathbb{E} \left[ x^{\zeta-1} (\Gamma) \aleph_{p_i, q_i, \sigma_i; r}^{m, n} \left[ h x^\zeta \left| \begin{matrix} (a_1, \mathfrak{A}_1, t), (a_j, \mathfrak{A}_j)_{2,n}, [\sigma_j(a_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1,m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right]; u \right] \\ &= \frac{1}{2\pi i} \int_{\mathcal{L}} \Phi(\eta, t) h^{-\eta} \Gamma(\zeta - \eta) u^{\zeta-\eta-1} d\eta. \end{aligned}$$

At last, after the little simplification and with the help of Eqs. (12) and (13), we arrive at desired result.

Our proof of Eq. (21) is much similar to that of (20).

#### 4. Fractional – order kinetic equations

Here, we derive the solution of modified FKEs involving the incomplete Aleph functions (12) and (14) and established some parallel corollaries.

Theorem 1. Let  $t > 0, v > 0, \omega > 0, c > 0, \zeta > 0, a_j, b_j, \mathfrak{A}_{ji}, \mathfrak{B}_{ji} \in \mathbb{C}, \mathfrak{A}_j > 0 (j = 1, \dots, p_i)$  and  $\mathfrak{B}_j > 0 (j = 1, \dots, q_i)$ , the modified FKE:

$$\begin{aligned} M(x) - M_0 x^{v-1} (\Gamma) \aleph_{p_i, q_i, \sigma_i; r}^{m, n} \left[ -\zeta^\omega x^\omega \left| \begin{matrix} (a_1, \mathfrak{A}_1, t), (a_j, \mathfrak{A}_j)_{2,n}, [\sigma_j(a_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1,m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right] \\ = -c^\omega {}_0D_x^{-\omega} M(x), \tag{22} \end{aligned}$$

where  ${}_0D_x^{-\omega}$  is the well-known Riemann-Liouville integral operator (Oldham and Spanier, 1974; Miller and Ross, 1993). Then there holds the solution as follows:

$$\begin{aligned} M(x) &= M_0 x^{v-1} \sum_{s=0}^{\infty} (-c^\omega x^\omega)^s \\ &(\Gamma) \aleph_{p_i+1, q_i+1, \sigma_i; r}^{m, n+1} \left[ -\zeta^\omega x^\omega \left| \begin{matrix} (a_1, \mathfrak{A}_1, t), (1-v, \omega), (a_j, \mathfrak{A}_j)_{2,n}, [\sigma_j(a_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1,m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i}, (1-v-\omega s, \omega) \end{matrix} \right. \right]. \tag{23} \end{aligned}$$

Proof. On applying the Elzaki transform (Elzaki, 2011; Singh et al., 2019a, 2019b) on both sides of (22), we have

$$\begin{aligned} \mathbb{E}[M(x); u] - \mathbb{E} \left[ M_0 x^{v-1} (\Gamma) \aleph_{p_i, q_i, \sigma_i; r}^{m, n} \left[ -\zeta^\omega x^\omega \left| \begin{matrix} (a_1, \mathfrak{A}_1, t), (a_j, \mathfrak{A}_j)_{2,n}, [\sigma_j(a_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1,m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right]; u \right] \\ = \mathbb{E}[-c^\omega {}_0D_x^{-\omega} M(x); u], \tag{24} \end{aligned}$$

using the result defined in (19), we arrive at

$$M(u) - M_0 \frac{1}{2\pi i} \int_{\mathcal{L}} \Phi(\eta, t) (-\zeta^\omega)^{-\eta} \mathbb{E}\{x^{v-\omega\eta-1}\} d\eta = -c^\omega u^\omega M(u),$$

where  $\Phi(\eta, t)$  is given by (13).

After little simplification the above equation can be express as

$$\begin{aligned} M(u) &= \frac{M_0}{(1+c^\omega u^\omega)} \frac{1}{2\pi i} \int_{\mathcal{L}} \Phi(\eta, t) (-\zeta^\omega)^{-\eta} \Gamma(v-\omega\eta) u^{v-\omega\eta+1} d\eta, \\ &= M_0 \sum_{s=0}^{\infty} (-c^\omega)^s \frac{1}{2\pi i} \\ &\times \int_{\mathcal{L}} \Phi(\eta, t) (-\zeta^\omega)^{-\eta} \Gamma(v-\omega\eta) u^{v+\omega s-\omega\eta+1} d\eta. \tag{25} \end{aligned}$$

Now, implementing the inverse Elzaki transform on both sides of (25), then

$$\begin{aligned} M(x) &= M_0 \sum_{s=0}^{\infty} (-c^\omega)^s \frac{1}{2\pi i} \int_{\mathcal{L}} \Phi(\eta, t) (-\zeta^\omega)^{-\eta} \Gamma(v-\omega\eta) \frac{x^{v+\omega s-\omega\eta-1}}{\Gamma(v+\omega s-\omega\eta)} d\eta, \\ M(x) &= M_0 x^{v-1} \sum_{s=0}^{\infty} (-c^\omega x^\omega)^s \frac{1}{2\pi i} \int_{\mathcal{L}} \Phi(\eta, t) (-\zeta^\omega)^{-\eta} \Gamma(v-\omega\eta) \frac{(x^\omega)^{-\eta}}{\Gamma(v+\omega s-\omega\eta)} d\eta. \end{aligned}$$

Finally, after rearrangement of terms, we obtained our desired solution (23).

Theorem 2. Let  $t > 0, v > 0, \omega > 0, c > 0, \zeta > 0, a_j, b_j, \mathfrak{A}_{ji}, \mathfrak{B}_{ji} \in \mathbb{C}, \mathfrak{A}_j > 0 (j = 1, \dots, p_i)$  and  $\mathfrak{B}_j > 0 (j = 1, \dots, q_i)$ , then the modified FKE:

$$M(x) - M_0 x^{v-1} \sum_{p_i, q_i, \sigma_i; r}^{m, n} \left[ -\zeta^\omega x^\omega \left| \begin{matrix} (\alpha_1, \mathfrak{A}_1, t), (\alpha_j, \mathfrak{A}_j)_{2, n}, [\sigma_j(\alpha_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1, m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right]$$

$$= -c^\omega {}_0D_x^{-\omega} M(x), \tag{26}$$

has the solution as follows:

$$M(x) = M_0 x^{v-1} \sum_{s=0}^{\infty} (-c^\omega x^\omega)^s$$

$$\times \sum_{p_i+1, q_i+1, \sigma_i; r}^{m, n+1} \left[ -\zeta^\omega x^\omega \left| \begin{matrix} (\alpha_1, \mathfrak{A}_1, t), (1-v, \omega), (\alpha_j, \mathfrak{A}_j)_{2, n}, [\sigma_j(\alpha_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1, m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i}, (1-v-\omega s, \omega) \end{matrix} \right. \right]. \tag{27}$$

Proof. We can get the proof of Theorem 2, in the same way as we did in Theorem 1.

**5. Special cases**

In this segment, we set up some significant corollaries of our leading results

**Corollary 1.** Let  $v > 0, \omega > 0, c > 0, \zeta > 0, \alpha_j, b_j, \mathfrak{A}_{ji}, \mathfrak{B}_{ji} \in \mathbb{C}, \mathfrak{A}_j > 0 (j = 1, \dots, p_i)$  and  $\mathfrak{B}_j > 0 (j = 1, \dots, q_i)$ , then the modified FKE:

$$M(x) - M_0 x^{v-1} \sum_{p_i, q_i, \sigma_i; r}^{m, n} \left[ -\zeta^\omega x^\omega \left| \begin{matrix} (\alpha_j, \mathfrak{A}_j)_{1, n}, [\sigma_j(\alpha_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1, m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right]$$

$$= -c^\omega {}_0D_x^{-\omega} M(x), \tag{28}$$

has holds the solution will be as follows:

$$M(x) = M_0 x^{v-1} \sum_{s=0}^{\infty} (-c^\omega x^\omega)^s$$

$$\times \sum_{p_i+1, q_i+1, \sigma_i; r}^{m, n+1} \left[ -\zeta^\omega x^\omega \left| \begin{matrix} (1-v, \omega), (\alpha_j, \mathfrak{A}_j)_{1, n}, [\sigma_j(\alpha_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1, m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i}, (1-v-\omega s, \omega) \end{matrix} \right. \right] \tag{29}$$

Proof. If we set  $\omega = 0$ , in (22), we arrive at the required result in terms of the Aleph-function (Chaurasia and Singh, 2012, 2014; Südländ et al., 1998, 2001) and which is known result recently obtained by Dutta et al. (2011; p. 44, Eq. (17)).

**Corollary 2.** Let  $v > 0, \omega > 0, c > 0, \zeta > 0, \alpha_j, b_j, \mathfrak{A}_{ji}, \mathfrak{B}_{ji} \in \mathbb{C}, \mathfrak{A}_j > 0 (j = 1, \dots, p_i)$  and  $\mathfrak{B}_j > 0 (j = 1, \dots, q_i)$ , then the modified FKE:

$$M(x) - M_0 x^{v-1} \sum_{p_i, q_i; r}^{m, n} \left[ -\zeta^\omega x^\omega \left| \begin{matrix} (\alpha_1, \mathfrak{A}_1, t), (\alpha_j, \mathfrak{A}_j)_{2, n}, [(\alpha_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1, m}, [(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right]$$

$$= -c^\omega {}_0D_x^{-\omega} M(x), \tag{30}$$

has the solution obtained in terms of the incomplete  $-I$  function as follows:

$$M(x) = M_0 x^{v-1} \sum_{s=0}^{\infty} (-c^\omega x^\omega)^s$$

$$\times \sum_{p_i+1, q_i+1; r}^{m, n+1} \left[ -\zeta^\omega x^\omega \left| \begin{matrix} (\alpha_1, \mathfrak{A}_1, t), (1-v, \omega), (\alpha_j, \mathfrak{A}_j)_{2, n}, [(\alpha_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1, m}, [(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i}, (1-v-\omega s, \omega) \end{matrix} \right. \right]. \tag{31}$$

Proof. If we set  $\sigma_j = 1$ , in (22), we arrive at the required result and which is recently attained by Bansal et al. (2020b; p. 5, Eq. (26)).

**Corollary 3.** Let  $v > 0, \omega > 0, c > 0, \zeta > 0, \alpha_j, b_j, \mathfrak{A}_{ji}, \mathfrak{B}_{ji} \in \mathbb{C}, \mathfrak{A}_j > 0 (j = 1, \dots, p_i)$  and  $\mathfrak{B}_j > 0 (j = 1, \dots, q_i)$ , then the modified FKE:

$$M(x) - M_0 x^{v-1} \sum_{p_i, q_i; r}^{m, n} \left[ -\zeta^\omega x^\omega \left| \begin{matrix} (\alpha_1, \mathfrak{A}_1, t), (\alpha_j, \mathfrak{A}_j)_{2, n}, [(\alpha_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1, m}, [(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i} \end{matrix} \right. \right]$$

$$= -c^\omega {}_0D_x^{-\omega} M(x), \tag{32}$$

has holds the solution will be as follows:

$$M(x) = M_0 x^{v-1} \sum_{s=0}^{\infty} (-c^\omega x^\omega)^s$$

$$\times \sum_{p_i+1, q_i+1; r}^{m, n+1} \left[ -\zeta^\omega x^\omega \left| \begin{matrix} (\alpha_1, \mathfrak{A}_1, t), (1-v, \omega), (\alpha_j, \mathfrak{A}_j)_{2, n}, [\sigma_j(\alpha_{ji}, \mathfrak{A}_{ji})]_{n+1, p_i} \\ (b_j, \mathfrak{B}_j)_{1, m}, [\sigma_j(b_{ji}, \mathfrak{B}_{ji})]_{m+1, q_i}, (1-v-\omega s, \omega) \end{matrix} \right. \right]. \tag{33}$$

Proof. Again, if we set  $\sigma_j = 1$ , in (26), we get the desired result and which is recently attained by Bansal et al. (2020b; p. 6, Eq. (28)).

**Corollary 4.** Let  $v > 0, \omega > 0, c > 0, \zeta > 0, x \in \mathbb{C} (-\infty, 0), \mu > 0, \delta, \lambda \in \mathbb{C}$ , then the modified FKE:

$$M(x) - M_0 x^{v-1} J_{\delta, \lambda}^\mu (-\zeta^\omega x^\omega) = -c^\omega {}_0D_x^{-\omega} M(x) \tag{34}$$

has holds the solution will be as follows:

$$M(x) = M_0 x^{v-1} \sum_{s=0}^{\infty} (-c^\omega x^\omega)^s$$

$$\times H_{2,4}^{1,2} \left[ -\zeta^\omega x^\omega \left| \begin{matrix} (1-v, \omega), (\lambda + \frac{\delta}{2}, 1) \\ (\lambda + \frac{\delta}{2}, 1), (\frac{\delta}{2}, 1), (\mu(\lambda + \frac{\delta}{2}) - \lambda - \delta, \mu), (1-v-\omega s, \omega) \end{matrix} \right. \right].$$

**Proof.** If we assign suitable value to the parameters in (12), then we have the following relation given in the monograph by Mathai et al. (2010; p.25, Eq. (1.139)),

$$J_{\delta, \lambda}^\mu(x) = H_{1,3}^{1,1} \left[ \frac{x^2}{4} \left| \begin{matrix} (\lambda + \frac{\delta}{2}, 1) \\ (\lambda + \frac{\delta}{2}, 1), (\frac{\delta}{2}, 1), (\mu(\lambda + \frac{\delta}{2}) - \lambda - \delta, \mu) \end{matrix} \right. \right],$$

where  $J_{\delta, \lambda}^\mu(x)$  is the generalized Bessel-Maitland function, and if we use this relation in (22), then after little simplification, we obtained the desired result given by (35).

**6. Numerical simulation**

In this part, we compute the results numerically for the MFKE (22) by assigning separate values to the distinct variables and parameters demonstrated through the Figs. 1–3. The effect of time and order of R-L integral operator of arbitrary order on the reaction rate is demonstrated in Figs. 1–3. It is observed from the Figs. 1–3 that the reaction rate decreases with enhancement of time and continuously depends on the value of fractional parameter.

**7. Conclusions**

We summarize this investigation by keeping in mind the potential uses and greatness of the KE in astrophysical problems. The objective of this paper is to figure out the reaction rate of particle by making use of MFKE for stars. A lot of authors have contributed to calculate the reaction rate of particle such as Saxena et al. (2002); (2004a; 2004b; 2008;), have a huge contribution to systematically studied the standard KE and generalized to FKE and expressed their results in the form of special functions which are used to figure out the variation of chemical composition in our solar system.

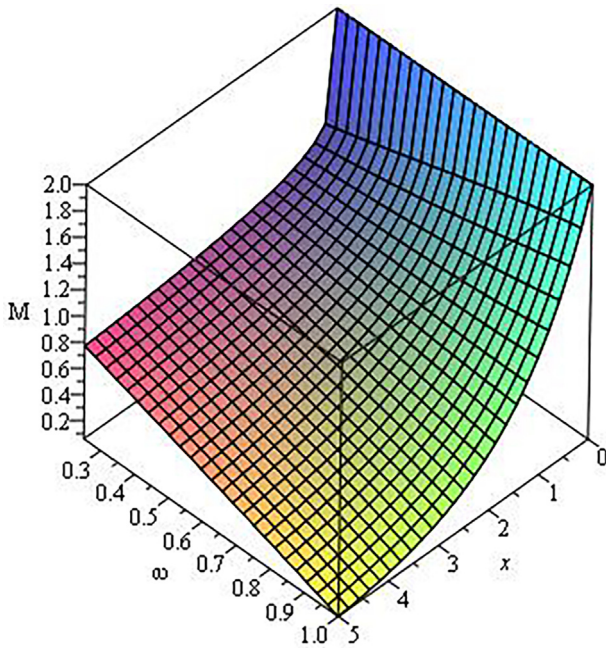


Fig. 1. Surface of solution when  $M_0 = 2, \zeta = 0$  and  $c = 0.7$ .

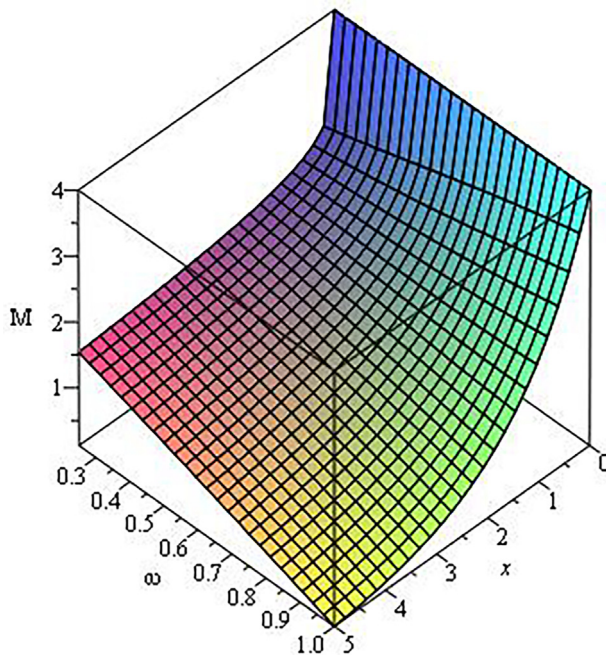


Fig. 2. Surface of solution when  $M_0 = 4, \zeta = 0$  and  $c = 0.7$ .

In the present work, we have investigated the modified FKE and derived the solution and this solution can play a vital role to figures out the reaction rate of the particle and with this, we have also established the Elzaki transform of R-L integral operator and IAF. The MFKE investigated in this article involving the incomplete Aleph functions and established the results in terms of special functions. From this work we can easily find out known and novel FKEs and their results respectively. It should be noted that the MFKE discussed here consist new and known results which are obtained very recently by Bansal et al. (2020c), Dutta et al. (2011), and these results hold here are also associated with the

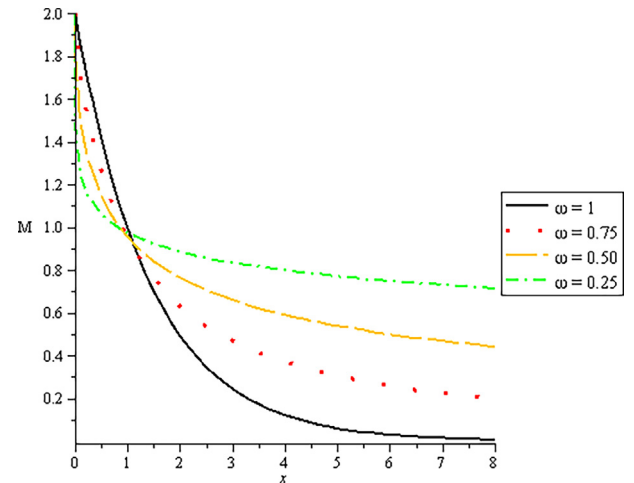


Fig. 3. Plots of solution when  $M_0 = 2, \zeta = 0$  and  $c = 0.7$  for different values of fractional parameter.

recent investigation of feasible astrophysical solution of solar system problems. In the solution of MFKE (6) given in Eqs. (23) and (27), the standard exponential decay is obtained for  $\omega = 1$ .

To validate the results discussed here, we plot the graphs and compute the results numerically for MFKE at distinct values of variables and parameters to show the behavior of reaction rate decreases with enhancement of time and continuously depends on the value of fractional parameter. All the novel results derived in this article have been come out by the use of incomplete special function for fractional calculus, notably the incomplete Aleph functions and by the application of the Elzaki transform.

Finally, the current investigation highlights the effectiveness and greatness of the MFKE involving the IAF by using the Elzaki transform and on the basis of this study we can say that it would be potentially useful in astrophysics. Such a potential connection needs further investigation.

#### CRediT authorship contribution statement

**Yudhveer Singh:** Investigation, Writing - original draft, Writing - review & editing. **Vinod Gill:** Formal analysis, Writing - original draft. **Jagdev Singh:** Conceptualization, Investigation, Writing - review & editing. **Devendra Kumar:** Conceptualization, Formal analysis, Methodology, Writing - original draft. **Ilyas Khan:** Formal analysis, Writing - original draft, Writing - review & editing.

#### Declaration of Competing Interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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