



On the soliton solutions to the modified Benjamin-Bona-Mahony and coupled Drinfel'd-Sokolov-Wilson models and its applications

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ARTICLE INFO

Article history:

Received 1 January 2018

Accepted 22 March 2018

Available online 29 March 2018

Keyword:

Modified Benjamin-Bona-Mahony equation

Drinfel'd-Sokolov-Wilson equation

Auxiliary equation method

ABSTRACT

In this article, the analytical solutions for modified Benjamin-Bona-Mahony and coupled Drinfel'd-Sokolov-Wilson equations have been extracted with the help of very simple transformation. These results hold numerous traveling wave solutions that are of key importance in elucidating some physical circumstance. The technique can also be functional to other sorts of nonlinear evolution equations in contemporary areas of research.

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1. Introduction

Nonlinear evolution equations (NEEs) have been studied in last few decades. A verity of NEEs are integrated with the help of various interesting computational techniques. To understand the physical structure, described by nonlinear partial differential equations (PDEs), exact solutions to the nonlinear PDEs play a crucial role in the study of the nonlinear models appearing in diverse disciplines; for instance, electromagnetic theory, geochemistry, astrophysics, fluid dynamics, elastic media, nuclear physics, optical fibers, high-energy physics, gravitation and in statistical and condensed matter physics, biology, solid state physics, chemical kinematics, chemical physics, electrochemistry, fluid dynamics, acoustics, cosmology and plasma physics etc, see (Seadawy and El-Rashidy, 2013; Gardner et al., 1967; Su and Gardner, 1969; Ito, 1980; Zhibin and Mingliang, 1993; Liang, 2014; Seadawy, 2012a, b; Seadawy, 2016a,b).

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Peer review under responsibility of King Saud University.



In recent few decades, growing interest have been drawn to find the analytical solutions for nonlinear wave equations, such as the traveling wave solution (Xu and Li, 2005), Cole-Hopf transformation, Painlevé method, Bäcklund transformation, amplitude ansatz method (Seadawy and Lu, 2017), sine-cosine method, Darboux transformation, Hirota method, function transformation method, Lie group analysis, extended simple equation method (Lu et al., 2017), homogeneous balance method (Chen et al., 2003), similarity reduced method, tanh method, fractional direct algebraic function method (Seadawy, 2016), inverse scattering method (Ablowitz and Clarkson, 1991), Hirota's bilinear method (Hirota, 1971), the homogeneous balance method (Wang, 1995), variational method (Khater et al., 2003), algebraic method (Khater et al., 2000), sine-cosine method, Jacobi elliptic function method (Liu et al., 2001), the F-expansion method (Zhou et al., 2003), extended Fan Sub-Equation method (Kalim and Younis, 2017), the (G'/G) expansion method (Abazari, 2010; Kutluay et al., 2010), the tanh and extended tanh method, extended direct algebraic method (Seadawy et al., 2016), the auxiliary equation method (Kalim and Seadawy, 2017) and many more (Yan et al., 2012; Grey and Tom, 2014; Mohapatra et al., 2015; Kalim and Seadawy, 2019; Abu Arqub et al., 2015; El-Ajou et al., 2015a,b; Abu Arqub, 2017a,b).

In this paper, the auxiliary equation method (AEM) is applied to construct the traveling wave solutions to the modified Benjamin-Bona-Mahony (m-BBM) and coupled Drinfel'd-Sokolov-Wilson (c-DSW) equations. The aim of the study is to deal with the explicit solutions of NPDEs and to explore the configuration of the physical

phenomena depending upon various parameters. As a result, some new and more general exact traveling wave solutions are obtained.

The Benjamin–Bona–Mahony equation (BBM) describes the uni-directional propagation of long waves in certain nonlinear dispersive media, as discussed in Seadawy (2018, 2017). The BBM equation is known as the modified BBM equation (mBBM) for $n = 2$. The governing equation is as follows:

$$u_t + u_x + \vartheta_1 u^n u_x + \vartheta_2 u_{xxx} = 0 \tag{1}$$

where the coefficients ϑ_i for $i = 1, 2$; are real constants.

The coupled Drinfeld–Sokolov–Wilson system (cDSW) reads

$$\left. \begin{aligned} u_t + \zeta_1 v v_x &= 0, \\ v_t + \zeta_2 v_{xxx} + \zeta_3 u v_x + \zeta_4 u_x v &= 0 \end{aligned} \right\} \tag{2}$$

where the coefficients ζ_i for $i = 1, 2, 3, 4$; are real constants, for details see Seadawy (2017), Seadawy et al. (2017), Wena et al. (2009), Seadawy and Alamri (2018), Khater et al. (2006).

This article has been devised as follows: in Section 2, the auxiliary equation method is introduced, while in Section 3, the solutions of the NPDEs have been presented. In last Section 4, the conclusions have been drawn.

2. The description of the auxiliary equation method

We will briefly present the AEM in the following steps:

Step 1. Let us have a general form of nonlinear PDE

$$F(u, u_t, u_x, u_{xx}, u_{xxx}, \dots) = 0. \tag{3}$$

where F is a polynomial function with respect to the indicated variables.

Step 2. The following wave variable is presented to solve (3)

$$u(x, t) = F(\xi), \tag{4}$$

The transformations (4) convert the PDE (3) to an ODE

$$O_i(F, F_\xi, F_{\xi\xi}, F_{\xi\xi\xi}, \dots), \tag{5}$$

where $F = F(\xi)$ is unknown function.

Step 3. The main idea of the auxiliary equation method based on expanding the traveling wave solution $F(\xi)$ of Eqs. (5) as a finite series

$$F(\xi) = \sum_{j=0}^n a_j \psi^j(\xi), \tag{6}$$

ψ satisfies

$$\frac{d\psi}{d\xi} = C_0 + C_1 \psi(\xi) + C_2 \psi^2(\xi) + C_3 \psi^3(\xi) + C_4 \psi^4(\xi), \tag{7}$$

$$\xi = \alpha x - \omega t \tag{8}$$

where $C_i (i = 0, 1, 2, 3, 4)$ and α are constants.

Step 4. Applying the homogenous balance to (3), the parameters n in (6) can be obtained.

Step 5. Substituting (6), (7) and (8) in (3) and collecting the coefficients of $\psi^j \psi^{(k)}$, then solving the system for ω and C_i .

Step 6. Substituting ω, C_i and $\psi(\xi)$ obtained in step 5 into (6), to obtain the solutions for (1) and (2).

3. Soliton extraction

3.1. Modified Benjamin–Bona–Mahony equation

Consider the transformation

$$u(x, t) = u(\xi), \quad \xi = \alpha x - \omega t, \tag{9}$$

using (9) into (1),

$$(\alpha - \omega)u' + \alpha \vartheta_1 u^2 u' - \alpha^2 \omega \vartheta_2 u''' = 0 \tag{10}$$

integrating

$$(\alpha - \omega)u + \frac{1}{3} \alpha \vartheta_1 u^3 - \alpha^2 \omega \vartheta_2 u'' = 0 \tag{11}$$

Consider the homogeneous balance between u^3 and u'' , gives $n = 3$. Suppose the solution of (11), is of the form

$$u = a_0 + a_1 \psi(\xi) + a_2 \psi(\xi)^2 + a_3 \psi(\xi)^3 \tag{12}$$

Substituting (6), (7) and (12) in (11) and collecting the coefficients of $\psi^j \psi^{(k)}$

Case I. $C_4 = 0$

(a).

$$\psi_1(\xi) = \frac{\sqrt{3}\sqrt{\alpha - \omega} \tan(\theta_1 \xi)}{\sqrt{\alpha} a_1 \sqrt{\vartheta_1}} + \frac{\sqrt{6}\sqrt{\alpha} \lambda_1 \sqrt{\vartheta_2} \sqrt{\omega}}{2 a_1 \sqrt{\vartheta_1}}, \tag{13}$$

where

$$\theta_1 = \frac{1}{2} \left(\frac{\sqrt{2}\sqrt{\omega}}{\alpha \sqrt{\vartheta_2} \sqrt{\alpha - \omega}} - \frac{\sqrt{2}}{\sqrt{\vartheta_2} \sqrt{\omega} \sqrt{\alpha - \omega}} \right).$$

The parameters C_i and a_j become

$$C_0 = \frac{-2\sqrt{6}\alpha - \sqrt{6}\alpha^2 c_1^2 \vartheta_2 \omega + 2\sqrt{6}\omega}{4\alpha^{3/2} a_1 \sqrt{\vartheta_1} \sqrt{\vartheta_2} \sqrt{\omega}}, \quad C_1 = \lambda_1, \quad C_2 = -\frac{a_1 \sqrt{\vartheta_1}}{\sqrt{6}\sqrt{\alpha} \sqrt{\vartheta_2} \sqrt{\omega}}, \quad C_3 = 0,$$

$$a_0 = \frac{\sqrt{6}\sqrt{\alpha} c_1 \sqrt{\vartheta_1} \sqrt{\vartheta_2} \omega^{3/2} - \sqrt{6}\alpha^{3/2} c_1 \sqrt{\vartheta_1} \sqrt{\vartheta_2} \sqrt{\omega}}{2(\alpha \vartheta_1 - \vartheta_1 \omega)}, \quad a_1 = \lambda_2, \quad a_2 = a_3 = 0, \text{ where } \lambda_1 \text{ and } \lambda_2 \text{ are arbitrary constants, hence the solution of (1) will be}$$

$$u_1(x, t) = \eta_1 \eta_2 \operatorname{sech}^2(\eta_1 \xi) \left(-2\alpha^2 \eta_1^2 \vartheta_2 \omega (\cosh(2\eta_1 \xi) - 2) \operatorname{sech}^2(\eta_1 \xi) + \alpha \eta_2^2 \vartheta_1 \tanh^2(\eta_1 \xi) + \alpha - \omega \right), \tag{14}$$

where

$$\eta_1 = \frac{\sqrt{\alpha - \omega}}{\sqrt{2}\alpha \sqrt{\vartheta_2} \sqrt{\omega}},$$

$$\eta_2 = -\frac{\sqrt{3}\sqrt{\alpha - \omega}}{\sqrt{\alpha} \sqrt{\vartheta_1}}.$$

(b).

$$\psi_2(\xi) = \frac{\sqrt{3}\sqrt{\alpha - \omega} \tan(\theta_1 \xi)}{\sqrt{\alpha} a_1 \sqrt{\vartheta_1}} - \frac{\sqrt{6}\sqrt{\alpha} \lambda_1 \sqrt{\vartheta_2} \sqrt{\omega}}{2 a_1 \sqrt{\vartheta_1}} \tag{15}$$

where

$$\theta_1 = \frac{1}{2} \left(\frac{\sqrt{2}}{\sqrt{\vartheta_2} \sqrt{\omega} \sqrt{\alpha - \omega}} - \frac{\sqrt{2}\sqrt{\omega}}{\alpha \sqrt{\vartheta_2} \sqrt{\alpha - \omega}} \right). \tag{16}$$

The parameters C_i and a_j become

$$C_0 = \frac{2\sqrt{6}\alpha + \sqrt{6}\alpha^2 c_1^2 \vartheta_2 \omega - 2\sqrt{6}\omega}{4\alpha^{3/2} a_1 \sqrt{\vartheta_1} \sqrt{\vartheta_2} \sqrt{\omega}}, \quad C_1 = \lambda_1, \quad C_2 = \frac{a_1 \sqrt{\vartheta_1}}{\sqrt{6}\sqrt{\alpha} \sqrt{\vartheta_2} \sqrt{\omega}},$$

$$C_3 = 0, \quad a_0 = \frac{\sqrt{6}\alpha^{3/2} c_1 \sqrt{\vartheta_1} \sqrt{\vartheta_2} \sqrt{\omega} - \sqrt{6}\sqrt{\alpha} c_1 \sqrt{\vartheta_1} \sqrt{\vartheta_2} \omega^{3/2}}{2(\alpha \vartheta_1 - \vartheta_1 \omega)}, \quad a_1 = \lambda_2, \quad a_2 = a_3 = 0,$$

where λ_1 and λ_2 are arbitrary constants, hence the solution of (1) will be

$$u_2(x, t) = \eta_1 \eta_2 \operatorname{sech}^2(\eta_1 \xi) \left(-2\alpha^2 \eta_1^2 \vartheta_2 \omega (\cosh(2\eta_1 \xi) - 2) \operatorname{sech}^2(\eta_1 \xi) + \alpha \eta_2^2 \vartheta_1 \tanh^2(\eta_1 \xi) + \alpha - \omega \right), \tag{17}$$

where

$$\eta_1 = \frac{\sqrt{\alpha - \omega}}{\sqrt{2\alpha\sqrt{\vartheta_2}\sqrt{\omega}}},$$

$$\eta_2 = \frac{\sqrt{3}\sqrt{\alpha - \omega}}{\sqrt{\alpha}\sqrt{\vartheta_1}}.$$

Case II. $C_3 = 0, C_4 = 0$

(a).

$$\psi_3(\xi) = \frac{\sqrt{6}\sqrt{\alpha}\lambda_1\sqrt{\vartheta_2}\sqrt{\omega}}{2a_1\sqrt{\vartheta_1}} - \frac{\sqrt{3}\sqrt{\alpha - \omega} \tan(\theta_1\xi)}{\sqrt{\alpha}a_1\sqrt{\vartheta_1}}, \quad (18)$$

where

$$\theta_1 = \frac{1}{2} \left(\frac{\sqrt{2}\xi}{\sqrt{\vartheta_2}\sqrt{\omega}\sqrt{\alpha - \omega}} - \frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha\sqrt{\vartheta_2}\sqrt{\alpha - \omega}} \right). \quad (19)$$

The parameters C_i and a_j become

$$C_0 = -\frac{\sqrt{\frac{3}{2}}(2\alpha + \alpha^2 c_1^2 \vartheta_2 \omega - 2\omega)}{2\alpha^{3/2} a_1 \sqrt{\vartheta_1} \sqrt{\vartheta_2} \sqrt{\omega}}, \quad C_1 = \lambda_1, \quad C_2 = -\frac{a_1 \sqrt{\vartheta_1}}{\sqrt{6}\sqrt{\alpha}\sqrt{\vartheta_2}\sqrt{\omega}},$$

$$a_0 = -\frac{\sqrt{\frac{3}{2}}\sqrt{\alpha}\lambda_1\sqrt{\vartheta_2}\sqrt{\omega}}{\sqrt{\vartheta_1}}, \quad a_1 = \lambda_2, \quad a_2 = 0, \quad a_3 = 0,$$

where λ_1 and λ_2 are arbitrary constants, hence the solution of (1) will be

$$u_3(x, t) = \eta_1 \eta_2 \operatorname{sech}^2(\eta_1 \xi) \left(-2\alpha^2 \eta_1^2 \vartheta_2 \omega (\cosh(2\eta_1 \xi) - 2) \operatorname{sech}^2(\eta_1 \xi) + \alpha \eta_2^2 \vartheta_1 \tanh^2(\eta_1 \xi) + \alpha - \omega \right) \quad (20)$$

where

$$\eta_1 = \frac{\sqrt{\alpha - \omega}}{\sqrt{2\alpha\sqrt{\vartheta_2}\sqrt{\omega}}},$$

$$\eta_2 = -\frac{\sqrt{3}\sqrt{\alpha - \omega}}{\sqrt{\alpha}\sqrt{\vartheta_1}}.$$

(b).

$$\psi_4(\xi) = \frac{1}{2} \left(\frac{2\sqrt{3}\sqrt{\alpha - \omega} \tan(\theta_1)}{\sqrt{\alpha}a_1\sqrt{\vartheta_1}} - \frac{\sqrt{6}\sqrt{\alpha}\lambda_1\sqrt{\vartheta_2}\sqrt{\omega}}{a_1\sqrt{\vartheta_1}} \right). \quad (21)$$

where

$$\theta_1 = \frac{1}{2} \left(\frac{\sqrt{2}\xi}{\sqrt{\vartheta_2}\sqrt{\omega}\sqrt{\alpha - \omega}} - \frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha\sqrt{\vartheta_2}\sqrt{\alpha - \omega}} \right). \quad (22)$$

The parameters C_i and a_j become

$$C_0 = \frac{\sqrt{\frac{3}{2}}(2\alpha + \alpha^2 c_1^2 \vartheta_2 \omega - 2\omega)}{2\alpha^{3/2} a_1 \sqrt{\vartheta_1} \sqrt{\vartheta_2} \sqrt{\omega}}, \quad C_1 = \lambda_1, \quad C_2 = \frac{a_1 \sqrt{\vartheta_1}}{\sqrt{6}\sqrt{\alpha}\sqrt{\vartheta_2}\sqrt{\omega}}, \quad a_0 = \frac{\sqrt{\frac{3}{2}}\sqrt{\alpha}\lambda_1\sqrt{\vartheta_2}\sqrt{\omega}}{\sqrt{\vartheta_1}},$$

$$a_1 = \lambda_2, \quad a_2 = 0, \quad a_3 = 0$$

where λ_1 and λ_2 are arbitrary constants, hence the solution of (1) will be

$$u_4(x, t) = \eta_1 \eta_2 (-\sec^2(\eta_1 \xi)) (-2\alpha^2 \eta_1^2 \vartheta_2 \omega (\cos(2\eta_1 \xi) - 2) \sec^2(\eta_1 \xi) - \alpha \eta_2^2 \vartheta_1 \tan^2(\eta_1 \xi) - \alpha + \omega) \quad (23)$$

where

$$\eta_1 = \frac{\sqrt{\alpha - \omega}}{\sqrt{2\alpha\sqrt{\vartheta_2}\sqrt{\omega}}},$$

$$\eta_2 = \frac{\sqrt{3}\sqrt{\alpha - \omega}}{\sqrt{\alpha}\sqrt{\vartheta_1}}.$$

(c).

$$\psi_5(\xi) = -\frac{\sqrt{3}\sqrt{\alpha - \omega} \tan(\theta_1 \xi)}{\sqrt{\alpha}a_1\sqrt{\vartheta_1}}, \quad (24)$$

where

$$\theta_1 = \frac{1}{2} \left(\frac{\sqrt{2}\xi}{\sqrt{\vartheta_2}\sqrt{\omega}\sqrt{\alpha - \omega}} - \frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha\sqrt{\vartheta_2}\sqrt{\alpha - \omega}} \right). \quad (25)$$

The parameters C_i and a_j become

$$C_0 = -\frac{\sqrt{\frac{3}{2}}\sqrt{\alpha^2 - 2\alpha\omega + \omega^2}}{\alpha^{3/2} a_1 \sqrt{\vartheta_1} \sqrt{\vartheta_2} \sqrt{\omega}}, \quad C_1 = 0, \quad C_2 = \frac{a_1 \sqrt{\vartheta_1} \sqrt{(\alpha - \omega)^2}}{\sqrt{6}\sqrt{\alpha}\sqrt{\vartheta_2}\sqrt{\omega}(\omega - \alpha)}, \quad a_0 = 0,$$

$$a_1 = \lambda_1, \quad a_2 = 0, \quad a_3 = 0$$

where λ_1 is arbitrary constant, hence the solution of (1) will be

$$u_5(x, t) = \eta_1 \eta_2 (-\sec^2(\eta_1 \xi)) (-2\alpha^2 \eta_1^2 \vartheta_2 \omega (\cos(2\eta_1 \xi) - 2) \sec^2(\eta_1 \xi) - \alpha \eta_2^2 \vartheta_1 \tan^2(\eta_1 \xi) - \alpha + \omega), \quad (26)$$

where

$$\eta_1 = \frac{\sqrt{\alpha - \omega}}{\sqrt{2\alpha\sqrt{\vartheta_2}\sqrt{\omega}}},$$

$$\eta_2 = -\frac{\sqrt{3}\sqrt{(\alpha - \omega)^2}}{\sqrt{\alpha}\sqrt{\vartheta_1}\sqrt{\alpha - \omega}}.$$

Case III. $C_0 = 0, C_4 = 0$

(a).

$$\psi_6(\xi) = \sqrt{\frac{-6\sqrt{3}\sqrt{\alpha}a_2\sqrt{\vartheta_1}\sqrt{\omega - \alpha}e^{2\theta_1\xi} - 6\sqrt{\omega - \alpha}e^{\theta_1\xi}}{1 - 3\alpha a_2^2 \vartheta_1 e^{2\theta_1\xi}}}, \quad (27)$$

where

$$\theta_1 = \frac{\sqrt{2}\sqrt{\omega - \alpha}}{\alpha\sqrt{\vartheta_2}\sqrt{\omega}}. \quad (28)$$

The parameters C_i and a_j become

$$C_1 = \frac{\sqrt{\omega - \alpha}}{\sqrt{2\alpha}\sqrt{\vartheta_2}\sqrt{\omega}}, \quad C_2 = 0, \quad C_3 = -\frac{a_2\sqrt{\vartheta_1}}{2\sqrt{6}\sqrt{\alpha}\sqrt{\vartheta_2}\sqrt{\omega}}, \quad a_0 = \frac{\sqrt{3}\sqrt{\omega - \alpha}}{\sqrt{\alpha}\sqrt{\vartheta_1}}, \quad a_1 = 0,$$

$$a_2 = \lambda_1, \quad a_3 = 0,$$

where λ_1 is arbitrary constant, hence the solution of (1) will be

$$u_6(x, t) = \frac{6\theta_1 \lambda_1 \sqrt{\omega - \alpha} e^{\theta_1 \xi}}{(1 - 3\alpha \lambda_1^2 \vartheta_1 e^{2\theta_1 \xi})^4} (9\alpha^2 \lambda_1^4 \vartheta_1^2 e^{4\theta_1 \xi} (23\alpha^2 \theta_1^2 \vartheta_2 \omega + 94(\alpha - \omega)) + 3\alpha \lambda_1^2 \vartheta_1 e^{2\theta_1 \xi} (23\alpha^2 \theta_1^2 \vartheta_2 \omega + 26(\omega - \alpha)) + 8\sqrt{3}\sqrt{\alpha}\lambda_1\sqrt{\vartheta_1}e^{\theta_1\xi}(\alpha^2\theta_1^2\vartheta_2\omega - \alpha + \omega) + \alpha^2\theta_1^2\vartheta_2\omega + 48\sqrt{3}\alpha^{3/2}\lambda_1^3\vartheta_1^{3/2}e^{3\theta_1\xi}(2\alpha^2\eta_1^2\vartheta_2\omega + \alpha - \omega) + 72\sqrt{3}\alpha^{5/2}\lambda_1^5\vartheta_1^{5/2}e^{5\theta_1\xi}(\alpha^2\eta_1^2\vartheta_2\omega + 11(\alpha - \omega)) + 27\alpha^3\lambda_1^6\vartheta_1^3e^{6\theta_1\xi}(\alpha^2\theta_1^2\vartheta_2\omega + 26(\alpha - \omega)) + 2\alpha - 2\omega). \quad (29)$$

(b).

$$\psi_7(\xi) = \frac{6\sqrt{\omega - \alpha}e^{\theta_1\xi}}{\sqrt{3}\sqrt{\alpha}a_1\sqrt{\vartheta_1}e^{\theta_1\xi} - 1}, \quad (30)$$

where

$$\theta_1 = \frac{\sqrt{2}\sqrt{\omega - \alpha}}{\alpha\sqrt{\vartheta_2}\sqrt{\omega}}. \quad (31)$$

The parameters C_i and a_j become

$$C_1 = \frac{\sqrt{2}\sqrt{\omega-\alpha}}{\alpha\sqrt{\vartheta_2}\sqrt{\omega}}, C_2 = -\frac{a_1\sqrt{\vartheta_1}}{\sqrt{6}\sqrt{\alpha}\sqrt{\vartheta_2}\sqrt{\omega}}, C_3 = 0, a_0 = -\frac{\sqrt{3}\sqrt{\omega-\alpha}}{\sqrt{\alpha}\sqrt{\vartheta_1}}, a_1 = \lambda_1, a_2 = a_3 = 0, \text{ where } \lambda_1 \text{ is arbitrary constant, hence the solution of (1) will be}$$

$$u_7(x, t) = -\frac{1}{(\sqrt{3}\sqrt{\alpha}\lambda_1\sqrt{\vartheta_1}e^{\theta_1\xi} - 1)^4} (6\theta_1\lambda_1\sqrt{\omega - \alpha}e^{\theta_1\xi} (3\alpha\lambda_1^2\vartheta_1e^{2\theta_1\xi}(\alpha^2\theta_1\vartheta_2\omega - 2\alpha + 2\omega) + \alpha^2\theta_1\vartheta_2(-\omega) - 8\sqrt{3}\sqrt{\alpha}\lambda_1\sqrt{\vartheta_1}(\alpha - \omega)e^{\theta_1\xi} - 2\alpha + 2\omega)). \tag{32}$$

3.2. Coupled Drinfel'd-Sokolov-Wilson equation

Consider the transformation

$$u(x, t) = u(\xi), \quad v(x, t) = v(\xi), \quad \xi = \alpha x - \omega t, \tag{33}$$

using (33) into (2),

$$-\omega u' + \alpha\zeta_1 v v' = 0 \tag{34a}$$

$$\alpha\zeta_4 u' v + \omega v' + \alpha\zeta_3 u v' + \alpha^3\zeta_2 v''' = 0 \tag{34b}$$

integrating (34a)

$$u = \frac{\alpha\zeta_1 v^2}{\omega} \tag{35}$$

and substituting in (34b)

$$\alpha^2\zeta_1(\zeta_3 + 2\zeta_4)v^2 v' + \alpha^3\zeta_2 v^{(3)}\omega - \omega^2 v' = 0 \tag{36}$$

integrating (36)

$$\frac{1}{3}\alpha^2\zeta_1(\zeta_3 + 2\zeta_4)v^3 + \alpha^3\zeta_2\omega v'' - \omega^2 v = 0 \tag{37}$$

Consider the homogeneous balance between v^3 and v'' , gives $n = 3$. Suppose the solution of (37), is of the form

$$u = a_0 + a_1\psi(\xi) + a_2\psi(\xi)^2 + a_3\psi(\xi)^3 \tag{38}$$

Substituting (6), (7) and (38) in (37) and collecting the coefficients of ψ^k

Case I. $C_4 = 0$
(a).

$$\psi_1(\xi) = \frac{\sqrt{3}\omega \tanh\left(\frac{\xi\sqrt{\omega}}{\sqrt{2\alpha^3/2}\sqrt{\zeta_2}}\right)}{\alpha a_1\sqrt{\zeta_1}\sqrt{\zeta_3 + 2\zeta_4}}. \tag{39}$$

The parameters C_i and a_j become

$$C_0 = \frac{\sqrt{3}\sqrt{\zeta_1}\sqrt{\zeta_3+2\zeta_4}\omega^{3/2}}{\sqrt{\alpha}\sqrt{\zeta_2}(a_1\alpha^2\zeta_1\zeta_3+2a_1\alpha^2\zeta_1\zeta_4)}, C_1 = 0, C_2 = -\frac{a_1\sqrt{\zeta_1}\sqrt{\zeta_3+2\zeta_4}}{\sqrt{6}\sqrt{\alpha}\sqrt{\zeta_2}\sqrt{\omega}}, C_3 = 0, a_0 = 0, a_1 = \lambda_1, a_2 = a_3 = 0, \text{ where } \lambda_1 \text{ is arbitrary constant, hence the solution of (2) will be}$$

$$v_1(x, t) = \frac{\sqrt{6}\omega^{7/2} \left(\cosh\left(\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}\right) - 2 \right) \operatorname{sech}^4\left(\frac{\xi\sqrt{\omega}}{\sqrt{2\alpha^3/2}\sqrt{\zeta_2}}\right)}{\alpha^{5/2}\sqrt{\zeta_1}\sqrt{\zeta_2}\sqrt{\zeta_3 + 2\zeta_4}}. \tag{40}$$

(b).

$$\psi_2(\xi) = -\frac{\sqrt{3}\omega \tanh\left(\frac{\xi\sqrt{\omega}}{\sqrt{2\alpha^3/2}\sqrt{\zeta_2}}\right)}{\alpha a_1\sqrt{\zeta_1}\sqrt{\zeta_3 + 2\zeta_4}}. \tag{41}$$

The parameters C_i and a_j become

$$C_0 = -\frac{\sqrt{3}\sqrt{\zeta_1}\sqrt{\zeta_3+2\zeta_4}\omega^{3/2}}{\sqrt{\alpha}\sqrt{\zeta_2}(a_1\alpha^2\zeta_1\zeta_3+2a_1\alpha^2\zeta_1\zeta_4)}, C_1 = 0, C_2 = \frac{a_1\sqrt{\zeta_1}\sqrt{\zeta_3+2\zeta_4}}{\sqrt{6}\sqrt{\alpha}\sqrt{\zeta_2}\sqrt{\omega}}, C_3 = 0, a_0 = 0, a_1 = \lambda_1, a_2 = a_3 = 0, \text{ where } \lambda_1 \text{ is arbitrary constant, hence the solution of (2) will be}$$

$$v_2(x, t) = -\frac{\sqrt{6}\omega^{7/2} \left(\cosh\left(\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}\right) - 2 \right) \operatorname{sech}^4\left(\frac{\xi\sqrt{\omega}}{\sqrt{2\alpha^3/2}\sqrt{\zeta_2}}\right)}{\alpha^{5/2}\sqrt{\zeta_1}\sqrt{\zeta_2}\sqrt{\zeta_3 + 2\zeta_4}}. \tag{42}$$

Case II. $C_0 = 0, C_4 = 0$
(a).

$$\psi_3(\xi) = \frac{\sqrt{6\omega\sqrt{\alpha^2\zeta_1(\zeta_3 + 2\zeta_4)}(-e^{\theta_1\xi})}(\sqrt{3}a_2\alpha^2\zeta_1(\zeta_3 + 2\zeta_4)e^{\theta_1\xi} + 1)}{\sqrt{3\alpha^4a_2^2\zeta_1^2(\zeta_3 + 2\zeta_4)^2e^{2\theta_1\xi} - 1}} \tag{43}$$

where

$$\theta_1 = \frac{\sqrt{2}\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}. \tag{44}$$

The parameters C_i and a_j become

$$C_1 = \frac{\sqrt{\omega}}{\sqrt{2\alpha^3/2}\sqrt{\zeta_2}}, C_2 = 0, C_3 = \frac{a_2\sqrt{\alpha^2\zeta_1(\zeta_3+2\zeta_4)}}{2\sqrt{6\alpha^3/2}\sqrt{\zeta_2}\sqrt{\omega}}, a_0 = \frac{\sqrt{3}\omega}{\sqrt{\alpha^2\zeta_1\zeta_3+2\alpha^2\zeta_1\zeta_4}}, a_1 = 0, a_2 = \lambda_1, a_3 = 0, \text{ where } \lambda_1 \text{ is arbitrary constant, hence the solution of (1) will be}$$

$$v_3(x, t) = \frac{24\sqrt{2}\lambda_1\omega^{7/2}\sqrt{\alpha^2\zeta_1(\zeta_3 + 2\zeta_4)}e^{\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}}}{\alpha^{3/2}\sqrt{\zeta_2}\left(\sqrt{3}\alpha^2\lambda_1\zeta_1(\zeta_3 + 2\zeta_4)e^{\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}} - 1\right)^4} \left(\alpha^2\lambda_1\zeta_1(\zeta_3 + 2\zeta_4)e^{\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}} \left(3\alpha^2\lambda_1\zeta_1(\zeta_3 + 2\zeta_4)e^{\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}} + 4\sqrt{3} \right) + 1 \right) \tag{45}$$

(b).

$$\psi_4(\xi) = -\frac{6\omega\sqrt{\alpha^2\zeta_1(\zeta_3 + 2\zeta_4)}e^{\theta_1\xi}}{\sqrt{3}a_1\alpha^2\zeta_1\zeta_3e^{\theta_1\xi} + 2\sqrt{3}a_1\alpha^2\zeta_1\zeta_4e^{\theta_1\xi} - 1}, \tag{46}$$

where

$$\theta_1 = \frac{\sqrt{2}\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}. \tag{47}$$

The parameters C_i and a_j become

$$C_1 = \frac{\sqrt{2}\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}, C_2 = \frac{a_1\sqrt{\alpha^2\zeta_1(\zeta_3+2\zeta_4)}}{\sqrt{6\alpha^3/2}\sqrt{\zeta_2}\sqrt{\omega}}, C_3 = 0, a_0 = \frac{\sqrt{3}\omega}{\sqrt{\alpha^2\zeta_1\zeta_3+2\alpha^2\zeta_1\zeta_4}}, a_1 = -\lambda_1, a_2 = a_3 = 0 \text{ where } \lambda_1 \text{ is arbitrary constant, hence the solution of (1) will be}$$

$$v_4(x, t) = -\frac{24\sqrt{2}\lambda_1\omega^{7/2}\sqrt{\alpha^2\zeta_1(\zeta_3 + 2\zeta_4)}e^{\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}}}{\alpha^{3/2}\sqrt{\zeta_2}\left(\sqrt{3}\alpha^2\lambda_1\zeta_1(\zeta_3 + 2\zeta_4)e^{\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}} + 1\right)^4} \left(\alpha^2\lambda_1\zeta_1(\zeta_3 + 2\zeta_4)e^{\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}} \left(3\alpha^2\lambda_1\zeta_1(\zeta_3 + 2\zeta_4)e^{\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}} - 4\sqrt{3} \right) + 1 \right) \tag{48}$$

Case III. $C_3 = 0, C_4 = 0$
(a).

$$\psi_5(\xi) = \frac{6\omega\sqrt{\alpha^2\zeta_1(\zeta_3 + 2\zeta_4)}e^{\theta_1\xi}}{\sqrt{3}a_1\alpha^2\zeta_1\zeta_3e^{\theta_1\xi} + 2\sqrt{3}a_1\alpha^2\zeta_1\zeta_4e^{\theta_1\xi} - 1} \tag{49}$$

where

$$\eta_1 = \frac{\sqrt{2}\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}} \tag{50}$$

The parameters C_i and a_j become

$$C_0 = 0, C_1 = \frac{\sqrt{2}\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}, C_2 = -\frac{a_1\sqrt{\alpha^2\zeta_1(\zeta_3+2\zeta_4)}}{\sqrt{6\alpha^{3/2}\sqrt{\zeta_2}\sqrt{\omega}}}, a_0 = -\frac{\sqrt{3}\omega}{\sqrt{\alpha^2\zeta_1\zeta_3+2\alpha^2\zeta_1\zeta_4}}$$

$a_1 = \lambda_1, a_2 = a_3 = 0$ where λ_1 is arbitrary constant, hence the solution of (2) will be

$$v_5(x, t) = \frac{24\sqrt{2}\lambda_1\omega^{7/2}\sqrt{\alpha^2\zeta_1(\zeta_3+2\zeta_4)}e^{\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}}}{\alpha^{3/2}\sqrt{\zeta_2}\left(\sqrt{3}\alpha^2\lambda_1\zeta_1(\zeta_3+2\zeta_4)e^{\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}}-1\right)^4}$$

$$\left(\alpha^2\lambda_1\zeta_1(\zeta_3+2\zeta_4)e^{\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}}(3\alpha^2\lambda_1\zeta_1(\zeta_3+2\zeta_4)e^{\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}}\right.$$

$$\left. (3\sqrt{3}\alpha^2\lambda_1\zeta_1(\zeta_3+2\zeta_4)e^{\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}}+2)-4\sqrt{3}\right)-1\Big), \tag{51}$$

(b).

$$\psi_6(\xi) = \frac{\sqrt{3}\omega \tanh\left(\frac{\xi\sqrt{\omega}}{\sqrt{2\alpha^{3/2}\sqrt{\zeta_2}}}\right)}{\alpha a_1\sqrt{\zeta_1}\sqrt{\zeta_3+2\zeta_4}} - \frac{a_0}{a_1} \tag{52}$$

The parameters C_i and a_j become

$$C_0 = \frac{3\omega^2 - \alpha^2 a_0^2 \zeta_1 (\zeta_3 + 2\zeta_4)}{\sqrt{6\alpha^{3/2} a_1 \sqrt{\zeta_1} \sqrt{\zeta_3 + 2\zeta_4} \sqrt{\omega}}}, C_1 = -\frac{\sqrt{3}a_0 \sqrt{\zeta_1} \sqrt{\zeta_3 + 2\zeta_4}}{\sqrt{\alpha} \sqrt{\zeta_2} \sqrt{\omega}},$$

$C_2 = -\frac{a_1 \sqrt{\zeta_1} \sqrt{\zeta_3 + 2\zeta_4}}{\sqrt{6\alpha} \sqrt{\zeta_2} \sqrt{\omega}}, a_0 = \lambda_1, a_1 = \lambda_2, a_2 = a_3 = 0$ where λ_1 and λ_2 are arbitrary constants, hence the solution of (2) will be

$$v_6(x, t) = \frac{\sqrt{6}\omega^{7/2}\left(\cosh\left(\frac{\sqrt{2}\xi\sqrt{\omega}}{\alpha^{3/2}\sqrt{\zeta_2}}\right)-2\right)\operatorname{sech}^4\left(\frac{\xi\sqrt{\omega}}{\sqrt{2\alpha^{3/2}\sqrt{\zeta_2}}}\right)}{\alpha^{5/2}\sqrt{\zeta_1}\sqrt{\zeta_2}\sqrt{\zeta_3+2\zeta_4}}, \tag{53}$$

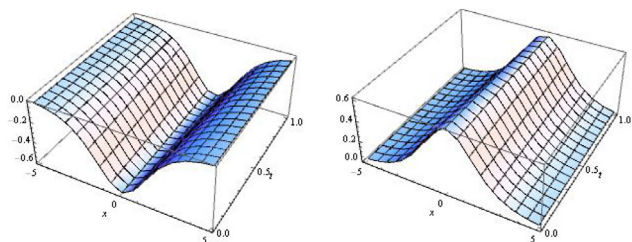
therefore, for $j = 1, 2, \dots, 6$

$$u_j(x, t) = \frac{\alpha\zeta_1 v_j^2(x, t)}{\omega} \tag{54}$$

4. Discussions and results

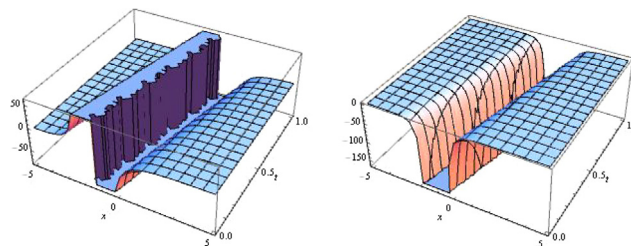
The graphical representation of solitons have been illustrated in the following figures, for various values of the parameters. Mathematica 10.4 is used to carried out simulations and to visualize the behavior of nonlinear waves. In Case I, the solution for the Eq. (1), is shown in Fig. 1 obtained from the Eq. (14) with $\vartheta_1 = 1, \vartheta_2 = 2, \alpha = 4, \omega = 2$, and Eq. (17) with $\vartheta_1 = 1, \vartheta_2 = 2, \alpha = 4, \omega = 2$, while in Case II, the solution for the Eq. (1), is shown in Fig. 2 obtained from the Eq. (20) with $\vartheta_1 = 3, \vartheta_2 = -1, \alpha = 4, \omega = -2$, Eq. (23) with $\vartheta_1 = 1, \vartheta_2 = -1, \alpha = 2, \omega = -3$ and Eq. (26) with $\vartheta_1 = 1, \vartheta_2 = -1, \alpha = 1, \omega = -1$. Moreover, in Case III, the solution for the Eq. (1), is shown in Fig. 3 obtained from the Eq. (29) with $\vartheta_1 = 3, \vartheta_2 = 2, \lambda_1 = 1, \alpha = 1, \omega = 2$ and Eq. (32) with $\vartheta_1 = 1, \vartheta_2 = 1, \lambda_1 = 2, \alpha = 1, \omega = 2$.

Similarly, the solution to the Eq. (2) for Case I, is shown in Fig. 4 obtained from the Eq. (40) with $\zeta_1 = 1, \zeta_2 = 1, \zeta_3 = 1, \zeta_4 = 1, \alpha = 2, \omega = 3$ and Eq. (42) with $\zeta_1 = 1, \zeta_2 = 2, \zeta_3 = 3, \zeta_4 = 4, \alpha = 2, \omega = 3$, while In Case II, the solution for the Eq. (2), is shown in Fig. 5 obtained from the Eqs. (45) with $\zeta_1 = 1, \zeta_2 = 1, \zeta_3 = 1, \zeta_4 = 1, \lambda_1 = 1, \alpha = 1, \omega = 1$ and Eq. (48) with $\zeta_1 = 1, \zeta_2 = -1, \zeta_3 = 2, \zeta_4 = 3, \lambda_1 = 1, \alpha = -1, \omega = 2$. Moreover, in Case III, the solution for the Eq. (2), is shown in Fig. 6 obtained from the Eq. (51) with $\zeta_1 = 1, \zeta_2 = 1, \zeta_3 = 1, \zeta_4 = 1, \lambda_1 = 1, \alpha = 1, \omega = 1$ and Eq. (53) with $\zeta_1 = 1, \zeta_2 = -5, \zeta_3 = 4, \zeta_4 = 3, \alpha = 5, \omega = -2$.



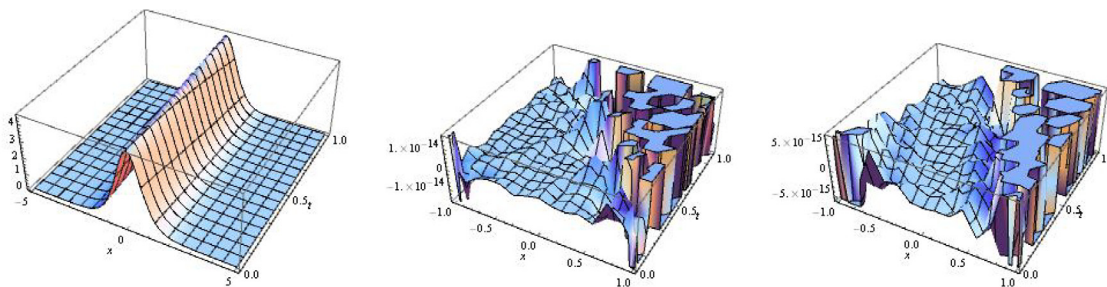
(a) $u_1(x, t): \vartheta_1=1, \vartheta_2=2, \alpha=4, \omega=2$
 (b) $u_2(x, t): \vartheta_1=1, \vartheta_2=2, \alpha=4, \omega=2$

Fig. 1. mBBM equation (Case I).



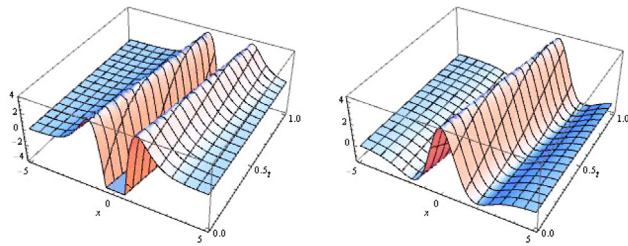
(a) $u_6(x, t): \vartheta_1=3, \vartheta_2=2, \lambda_1=1, \alpha=1, \omega=2$
 (b) $u_7(x, t): \vartheta_1=1, \vartheta_2=1, \lambda_1=2, \alpha=1, \omega=2$

Fig. 3. mBBM equation (Case III).



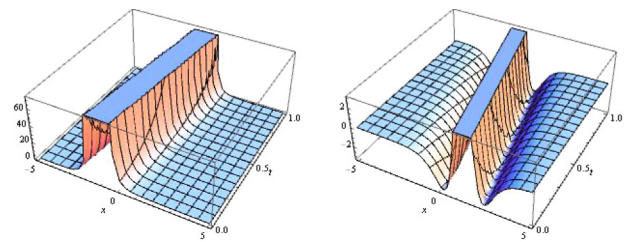
(a) $u_3(x, t): \vartheta_1=3, \vartheta_2=-1, \alpha=4, \omega=-2$
 (b) $u_4(x, t): \vartheta_1=1, \vartheta_2=-1, \alpha=2, \omega=-3$
 (c) $u_5(x, t): \vartheta_1=1, \vartheta_2=-1, \alpha=1, \omega=-1$

Fig. 2. mBBM equation (Case II).



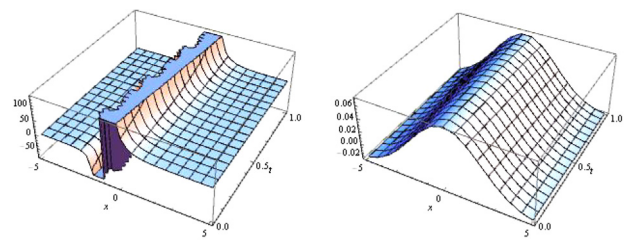
(a) $v_1(x,t)$: $\varsigma_1=1$, $\varsigma_2=1$, (b) $v_2(x,t)$: $\varsigma_1=1$, $\varsigma_2=2$,
 $\varsigma_3=1$, $\varsigma_4=1$, $\alpha=2$, $\omega=3$ $\varsigma_3=3$, $\varsigma_4=4$, $\alpha=2$, $\omega=3$

Fig. 4. cDSW system (Case I).



(a) $v_3(x,t)$: $\varsigma_1=1$, $\varsigma_2=1$, (b) $v_4(x,t)$: $\varsigma_1=1$, $\varsigma_2=-1$,
 $\varsigma_3=1$, $\varsigma_4=1$, $\lambda_1=1$, $\alpha=1$, $\varsigma_3=2$, $\varsigma_4=3$, $\lambda_1=1$, $\alpha=-1$,
 $\omega=1$ $\omega=2$

Fig. 5. cDSW system (Case II).



(a) $v_5(x,t)$: $\varsigma_1=1$, $\varsigma_2=1$, (b) $v_6(x,t)$: $\varsigma_1=1$, $\varsigma_2=-5$,
 $\varsigma_3=1$, $\varsigma_4=1$, $\lambda_1=1$, $\alpha=1$, $\varsigma_3=4$, $\varsigma_4=3$, $\alpha=5$, $\omega=-2$
 $\omega=1$

Fig. 6. cDSW system (Case III).

5. Conclusion

The aim of the study is to find some new traveling-wave solutions for modified Benjamin-Bona-Mahony and Drinfel'd-Sokolov-Wilson equations. It is observed that the auxiliary equation method is one of the most powerful tools to find a variety of analytical solutions for more complex problems. Depending on the real parameters, a collection of new exact solutions are obtained, for details see Figs. 1–6. These results are very auspicious for further investigation and stances on a strong basis for the solution of NPDEs.

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