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Original article

# Bright and singular soliton solutions to the Atangana-Baleanu fractional system of equations for the ISALWs



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#### 1. Introduction

Over the past few years, the search for new results of fractional differential equations and especially nonlinear evolution types (NLFEEs) have captured the interest of many scientists in different areas of science and engineering. Seeking the solution of these types of equations in the form of travelling wave play an important role in understanding some ofthe real-life physical phenomena with a particular interest in nonlinear models. These nonlinear models may appear in different areas of science including plasma physics, optical fibers, fluid dynamics, biology, and solid-state physics. Hence, it is an important topic to find wave solutions for these types of equations to better understand their nature. Numerous methods have been utilized to reveal these solutions such as theG'/G-expansion method (Abazariet al., 2016; Abazari, 2013),

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### ABSTRACT

This work searches for new soliton solutions to the Atangana-Baleanu (AB) fractional system of equations for the ion sound and Langmuir waves (ISALWs). A new auxiliary equation scheme (NAES) is implemented to solve this model with the aid of a symbolic software. The hyperbolic and trigonometric function forms of this equation have been obtained. Due to the good performance of the NAEM, it is believed that this method is a promising technique to handle a wide variety of AB fractional evolution systems. © 2021 The Author(s). Published by Elsevier B.V. on behalf of King Saud University. This is an open access article under the CC BY-NC-ND license (http://creativecommons.org/licenses/by-nc-nd/4.0/).

first integral method (Aminikhah et al., 2015; Çenesiz et al., 2017), Jacobi elliptic function expansion scheme (Kurt, 2019; Tasbozan et al., 2016), Exp-function method (Hosseini et al., 2020a, 2020b), expanded sinh-Gordon system expansion scheme (Sulaiman et al. 2020; Bulut et al. 2018a, 2018b), modified Kudryashov method (Rezazadeh et al., 2019a; Biswas et al., 2018), fractional Sine-Gordon Equation method (Rezazadeh et al., 2019b; Korkmaz et al., 2020), modified auxiliary equation method (Khater et al., 2019a, 2019b) and much more relative methods (Akinyemiet al. (2021a, 2021b); Şenol et al. (2019); Akinyemi 2020; Hashemi and Akgül, 2018; Hashemi, 2018; Najafiet al., 2017; Ghanbariet al., 2020, 2019; Rahmanet al., 2020; Munusamyet al., 2020; Hosseini et al., 2020c; Rizvi et al., 2021, 2020a, 2020b, 2020c, 2020d; Younis et al., 2021; Younis et al. 2020a; Younis et al. 2020b; Wanget al. 2014).

This manuscript aims at findingsome new form of soliton solutions for the system with AB fractional-order derivative of the ISALWs defined for  $\alpha = 1$  from (Yajima and Oikawa, 1976) as

$$\begin{split} tABRD_{0^{+}}^{\alpha}E + \frac{1}{2}\frac{\partial^{2}E}{\partial x^{2}} - nE &= 0, t > 0, \quad 0 < \alpha \leqslant 1. \\ tABRD_{0^{+}}^{\alpha}n - \frac{\partial^{2}n}{\partial x^{2}} - 2\frac{\partial^{2}(|E|^{2})}{\partial x^{2}} &= 0, \end{split}$$
(1)

where *n* can be defined as the perturbation with normalized density and  $Ee^{-iw_p t}$  is the normalized electric field associated with the Lang-

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muir oscillations (Yajima and Oikawa, 1976). Both *x* and *t* variables are normalized and  $tABRD_{0^+}^{\alpha}$  are the AB fractional operator with order  $\alpha \in (0, 1)$  in the *t*- direction defined as (Atangana and Koca, 2016; Atangana and Gómez-Aguilar, 2018).

$$tABRD_{a^{+}}^{\alpha}f(t) = \frac{\varpi(\alpha)}{1-\alpha} \frac{d}{dt} \int_{a}^{t} f(x)\Xi_{\alpha}\left(\frac{-\alpha(t-\alpha)^{\alpha}}{1-\alpha}\right) dx, \tag{2}$$

Where  $\Xi_{\boldsymbol{\alpha}}(.)$  is the one parameter Mittag-Leffler function, provided in the form

$$\Xi_{\alpha}\left(\frac{-\alpha(t-\alpha)^{\alpha}}{1-\alpha}\right) = \sum_{n=0}^{\infty} \frac{\left(\frac{-\alpha}{1-\alpha}\right)^{r}(t-x)^{\alpha r}}{\Gamma(\alpha r+1)},$$

and  $\varpi(\alpha)$  can be defined as the normalization function. Thus, the AB fractional operator for f(t) becomes

$$tABRD_{a^+}^{\alpha}f(t) = \frac{\varpi(\alpha)}{1-\alpha}\sum_{r=0}^{\infty}\left(\frac{-\alpha}{1-\alpha}\right)^r \quad RLI_a^{\alpha r}f(t).$$

The organization of the paper is as follows: the section 2 shows the introduction of the major ideas and steps of the NAEM. Section 3 describes thefour new soliton solutions to system (1) involving different parameters. In section 4 two-dimensional and threedimensional graphs are presented to illustrate some physical features of the obtained results. Finally, section 5 gives detailed conclusions.

#### 2• Methods

The new auxiliary equation scheme was first presented by Sirendaoreji (Sirendaoreji, 2006) to help in finding new wave results for some nonlinear partial differential equations. The method depends on some basic steps beginning with considering the following NLFNEE with *u* which is a dependent variable as

$$K(\quad tABRD_{0^{+}}^{\alpha}u, \frac{\partial u}{\partial x}, \quad tABRD_{0^{+}}^{2\alpha}u, \frac{\partial^{2}u}{\partial x^{2}}, \ldots) = 0,$$
  
$$t > 0, \qquad 0 < \alpha \leq 1,$$
(3)

where*K* is a polynomial in*u*.We shall use the wave transformation as (Yue et al., 2020; Khater et al., 2020; Park et al., 2020) in the form

$$u(x,t) = u(\eta), \eta = x + \frac{\kappa(1-\alpha)t^{-r}}{B(\alpha)\sum_{r=0}^{\infty} \left(-\frac{\alpha}{1-\alpha}\right)^r \Gamma(1-\alpha r)}, \quad \kappa \neq 0,$$
(4)

which can be used to convert Eq. (3) into a nonlinear ODE in the form

$$J(u, u', u'', u''', \ldots) = 0,$$
(5)

where u is a function in $\eta$  and the prime denotes the differentiation for $\eta$ . For the solution of Eq. (5), we assume that the solution takes the following form

$$u(\eta) = \sum_{j=0}^{M} B_j \Phi^j(\eta), \tag{6}$$

where  $B_j(0 \le j \le M)$  are parameters to be determinate later. We reach *M* by plugging Eq. (14) into Eq. (5) and equating the highest derivative and nonlinear terms together. The function  $\Phi(\eta)$  simplifies the first-order nonlinear ODEs as

$$\left(\frac{d\Phi}{d\eta}\right)^2 = m_1 \Phi^2(\eta) + m_2 \Phi^4(\eta) + m_3 \Phi^6(\eta), \tag{7}$$

where  $m_1, m_2$  and  $m_3$  are constants. Then, by plugging Eq. (6) into Eq. (5) and utilizing Eq. (7) when required, we reach a class of algebraic equations for  $B_j(0 \le j \le M), m_1, m_2, m_3$  and  $\kappa$ . With some manipulations, we evaluate the class of equations, and find the values  $B_j(0 \le j \le M), m_1, m_2, m_3$  and  $\kappa$ . The general solutions of Eq. (15) are given as

$$\Phi_{1}(\eta) = \left(\frac{-m_{1}m_{2}\mathrm{sech}^{2}(\sqrt{m_{1}}\eta)}{m_{2}^{2} - m_{1}m_{3}(1 + \varepsilon \mathrm{tanh}(\sqrt{m_{1}}\eta))^{2}}\right)^{\frac{1}{2}}, \quad m_{1} > 0.$$
(8)

$$\Phi_{2}(\eta) = \left(\frac{m_{1}m_{2}\mathrm{csch}^{2}(\sqrt{m_{1}}\eta)}{m_{2}^{2} - m_{1}m_{3}(1 + \varepsilon \mathrm{coth}(\sqrt{m_{1}}\eta))^{2}}\right)^{\frac{1}{2}}, \quad m_{1} > 0.$$
(9)

$$\Phi_3(\eta) = \left(\frac{2m_1}{\varepsilon\sqrt{\Delta}\cosh(2\sqrt{m_1}\eta) - m_2}\right)^{\frac{1}{2}}, \quad m_1 > 0, \Delta > 0.$$
(10)

$$\Phi_4(\eta) = \left(\frac{2m_1}{\varepsilon\sqrt{\Delta}\cos(2\sqrt{-m_1}\eta) - m_2}\right)^{\frac{1}{2}}, \quad m_1 < 0, \Delta > 0.$$
(11)

$$\Phi_5(\eta) = \left(\frac{2m_1}{\varepsilon\sqrt{-\Delta}\sinh(2\sqrt{m_1}\eta) - m_2}\right)^{\frac{1}{2}}, \quad m_1 > 0, \Delta < 0.$$
(12)

$$\Phi_6(\eta) = \left(\frac{2m_1}{\varepsilon\sqrt{\Delta}\sin(2\sqrt{-m_1}\eta) - m_2}\right)^{\frac{1}{2}}, \quad m_1 < 0, \Delta > 0.$$
(13)

$$\Phi_{7}(\eta) = \left(\frac{-m_{1}\mathrm{sech}^{2}(\sqrt{m_{1}}\eta)}{m_{2}^{2} - 2\varepsilon\sqrt{m_{1}m_{3}}\mathrm{tanh}(\sqrt{m_{1}}\eta)}\right)^{\frac{1}{2}}, \quad m_{1}, m_{3} > 0.$$
(14)

$$\Phi_{8}(\eta) = \left(\frac{-m_{1}\sec^{2}(\sqrt{-m_{1}}\eta)}{m_{2}^{2} + 2\varepsilon\sqrt{-m_{1}m_{3}}\tan(\sqrt{-m_{1}}\eta)}\right)^{\frac{1}{2}}, \quad m_{1} < 0, m_{3} > 0.$$
(15)

$$\Phi_9(\eta) = \left(\frac{m_1 \operatorname{csch}^2(\sqrt{m_1}\eta)}{m_2^2 + 2\varepsilon\sqrt{m_1m_3}\operatorname{coth}(\sqrt{m_1}\eta)}\right)^{\frac{1}{2}}, \quad m_1 > 0, m_3 > 0.$$
(16)

$$\Phi_{10}(\eta) = \left(\frac{-m_1 \csc(\sqrt{-m_1}\eta)}{m_2^2 + 2\varepsilon\sqrt{-m_1m_3}\tanh(\sqrt{-m_1}\eta)}\right)^{\frac{1}{2}}, \quad m_1 < 0, m_3 > 0.$$
(17)

$$\Phi_{11}(\eta) = \left(-\frac{m_1}{m_2}(1 + \varepsilon \tanh(\frac{\sqrt{m_1}}{2}\eta))\right)^{\frac{1}{2}}, \quad m_1 > 0, \Delta = 0.$$
(18)

$$\Phi_{12}(\eta) = \left(-\frac{m_1}{m_2}(1 + \varepsilon \coth(\frac{\sqrt{m_1}}{2}\eta))\right)^{\frac{1}{2}}, \quad m_1 > 0, \Delta = 0.$$
(19)

$$\Phi_{13}(\eta) = 4 \left( \frac{m_1 e^{2\varepsilon \sqrt{m_1}\eta}}{\left( e^{2\varepsilon \sqrt{m_1}\eta} - 4m_2 \right)^2 - 64m_1 m_3} \right)^{\frac{1}{2}} \quad m_1 > 0.$$
 (20)

$$\Phi_{14}(\eta) = 4 \left( \frac{\pm m_1 e^{2\varepsilon \sqrt{m_1}\eta}}{(1 - 64m_1 m_3 e^{4\varepsilon \sqrt{m_1}\eta})} \right)^{\frac{1}{2}}, \quad m_1 > 0, m_2 = 0,$$
(21)

where  $\Delta = m_2^2 - 4m_1m_3$  and  $\varepsilon = \pm 1$ . Hence, the multiple exact solutions to the NLFNEE of Eq. (5) can be reached by considering Eq. (6) along with Eqs. (8)-(21).

Next, we will investigate the application of the previous illustrated method for solving the system of Eq. (1).

#### 3. Exact bright and singular solitons of system (1)

In this section, the effectiveness of the methodis being tested for solving equation Eq. (1). First, assume that

$$E(\mathbf{x}, t) = u(\eta)e^{i\mu}, \quad n(\mathbf{x}, t) = v(\eta),$$
  

$$\mu = k\mathbf{x} + \frac{\omega(1-\alpha)t^{-r}}{B(\alpha)\sum_{r=0}^{\infty} \left(-\frac{\pi}{1-\alpha}\right)^r \Gamma(1-\alpha r)},$$
  

$$\eta = \gamma \mathbf{x} + \frac{\beta(1-\alpha)t^{-r}}{B(\alpha)\sum_{r=0}^{\infty} \left(-\frac{\pi}{1-\alpha}\right)^r \Gamma(1-\alpha r)},$$
(22)

where  $\beta$  and  $\omega$  are considered constants. Then, by plugging Eq. (22) into Eq. (1) yields the following

$$\frac{1}{2}\gamma^2 u'' + i(\beta + k\gamma)u' - 0.5(k^2 + 2w)u - uv = 0,$$
(23)

$$(\beta^2 - \gamma^2) v'' + 4\gamma^2 (u^{\prime 2} - uu'') = 0.$$
<sup>(24)</sup>

By dividing the resulting equation into real and imaginary parts which provide

$$\beta = -k\gamma, \tag{25}$$

and then by double integrating Eq. (24) with respect to  $\eta,$  we reach

$$\nu = \frac{2\gamma^2}{\beta^2 - \gamma^2} u^2 = \frac{2}{k^2 - 1} u^2.$$
(26)

Plugging Eq. (25) and Eq. (26) into Eq. (23), finally results in

$$u'' - \frac{4}{\gamma^2 (k^2 - 1)} u^3 - \frac{(k^2 + 2w)}{\gamma^2} u = 0,$$
(27)

$$u'' = \frac{(k^2 + 2w)}{\gamma^2} u + \frac{4}{\gamma^2 (k^2 - 1)} u^3.$$
(28)

Fo the last step, we balance the two terms of u'' and  $u^3$  with the aid of homogeneous principle which will provide M = 1. With M = 1, Eq. (28) has the form

$$u(\eta) = B_0 + B_1 \Phi(\eta), \tag{29}$$

with  $B_0$  and  $B_1$  being constant terms to be determined. Finally, replacing Eq. (29) into Eq. (28) by the fact that Eq. (7) is satisfied to adjust all coefficients of  $\Phi^i(\eta)$  for  $(i = 0, 1, 2, \cdots)$  to zero, we reach an algebraic class of systems, which can be simplified as

$$n_{0} = 0, \quad n_{1} = \pm \frac{1}{2} \sqrt{2\gamma^{2} m_{2}(k^{2} - 1)}, \quad m_{3} = 0,$$
  

$$\omega = \frac{1}{2} \left(\gamma^{2} m_{1} - k^{2}\right). \quad (30)$$

The following cases can be considered:

#### **Case.** *I*: When $m_1 > 0$ , the solution takes the form

$$E_{1}^{\pm}(\mathbf{x},t) = \pm \frac{\gamma \sqrt{-2m_{1}(k^{2}-1)}}{2} \operatorname{sech}\left(\sqrt{m_{1}}\left(\gamma \mathbf{x} - \frac{\beta(\alpha-1)t^{-r}}{B(\alpha)\sum_{r=0}^{\infty}\left(-\frac{x}{1-\alpha}\right)^{r}\Gamma(1-\alpha r)}\right)\right) \times \exp\left(i\left(k\mathbf{x} + \frac{(\gamma^{2}m_{1}-k^{2})(1-\alpha)t^{-r}}{2B(\alpha)\sum_{r=0}^{\infty}\left(-\frac{x}{1-\alpha}\right)^{r}\Gamma(1-\alpha r)}\right)\right),$$

$$n_{1}(\mathbf{x},t) = -\gamma^{2}m_{1}\operatorname{sech}^{2}\left(\sqrt{m_{1}}\left(\gamma \mathbf{x} + \frac{\beta(1-\alpha)t^{-r}}{B(\alpha)\sum_{r=0}^{\infty}\left(-\frac{x}{1-\alpha}\right)^{r}\Gamma(1-\alpha r)}\right)\right),$$
(31)

Journal of King Saud University – Science 33 (2021) 101420

$$E_{2}^{\pm}(\mathbf{x},t) = \pm \frac{\gamma\sqrt{2m_{1}(k^{2}-1)}}{2} \operatorname{csch}\left(\sqrt{m_{1}}\left(\gamma \mathbf{x} + \frac{\beta(1-\alpha)t^{-r}}{B(\alpha)\sum_{r=0}^{\infty}\left(-\frac{\alpha}{1-\alpha}\right)^{r}\Gamma(1-\alpha r)}\right)\right) \times \exp\left(i\left(k\mathbf{x} + \frac{(\gamma^{2}m_{1}-k^{2})(1-\alpha)t^{-r}}{2B(\alpha)\sum_{r=0}^{\infty}\left(-\frac{\alpha}{1-\alpha}\right)^{r}\Gamma(1-\alpha r)}\right)\right),$$

$$n_{2}(\mathbf{x},t) = \gamma^{2}m_{1}\operatorname{sech}^{2}\left(\sqrt{m_{1}}\left(\gamma \mathbf{x} + \frac{\beta(1-\alpha)t^{-r}}{B(\alpha)\sum_{r=0}^{\infty}\left(-\frac{\alpha}{1-\alpha}\right)^{r}\Gamma(1-\alpha r)}\right)\right),$$
(32)

$$E_{3}^{\pm}(\mathbf{x},t) = \pm \sqrt{\frac{m_{1}\gamma^{2}(k^{2}-1)}{\cosh\left(2\sqrt{m_{1}}\left(\gamma \mathbf{x} + \frac{\beta(1-\alpha)t^{-r}}{B(\alpha)\sum_{r=0}^{\infty}\left(-\frac{\alpha}{1-\alpha}\right)^{r}\Gamma(1-\alpha r)}\right)\right)^{-1}} \times \exp\left(i\left(kx + \frac{\left(\gamma^{2}m_{1}-k^{2}\right)(1-\alpha)t^{-r}}{2B(\alpha)\sum_{r=0}^{\infty}\left(\frac{\alpha}{\alpha-1}\right)^{r}\Gamma(1-\alpha r)}\right)\right),$$

$$n_{3}(x,t) = \frac{2m_{1}\gamma^{2}}{\cosh\left(2\sqrt{m_{1}}\left(\gamma x + \frac{\beta(1-x)t^{-r}}{B(x)\sum_{r=0}^{\infty}\left(-\frac{z}{1-x}\right)^{r}\Gamma(1-xr)}\right)\right)^{-1}},$$
(33)

$$E_{4}^{\pm}(\mathbf{x},t) = \pm \sqrt{\frac{m_{1}\gamma^{2}(k^{2}-1)}{i\sinh\left(2\sqrt{m_{1}}\left(\gamma \mathbf{x}-\frac{\beta(\alpha-1)t^{-r}}{B(\alpha)\sum_{r=0}^{\infty}\left(-\frac{\alpha}{1-2}\right)^{r}\Gamma(1-\alpha r)}\right)\right)^{-1}} \times \exp\left(i\left(k\mathbf{x}+\frac{(\gamma^{2}m_{1}-k^{2})(1-\alpha)t^{-r}}{2B(\alpha)\sum_{r=0}^{\infty}\left(\frac{\alpha}{2-1}\right)^{r}\Gamma(1-\alpha r)}\right)\right),$$

$$n_{4}(x,t) = \frac{2m_{1}\gamma^{2}}{i\sinh\left(2\sqrt{m_{1}}\left(\gamma x + \frac{\beta(1-\alpha)t^{-r}}{B(\alpha)\sum_{r=0}^{\infty}\left(-\frac{\alpha}{1-\alpha}\right)^{r}\Gamma(1-\alpha r)}\right)\right)^{-1}},$$
(34)

$$E_{5}^{\pm}(x,t) = \frac{\sqrt{\sum_{\substack{8\gamma^{2}m_{1}m_{2}(k^{2}-1)e}}^{2\sqrt{m_{1}}} \left( \sum_{\substack{\gamma x + \frac{\beta(1-x)t^{-r}}{B(x)\sum_{r=0}^{\infty} \left(-\frac{x}{1-x}\right)^{r} \Gamma(1-xr)}} \right)}}{e^{2\sqrt{m_{1}} \left( \sum_{\substack{\gamma x + \frac{\beta(1-x)t^{-r}}{B(x)\sum_{r=0}^{\infty} \left(-\frac{x}{1-x}\right)^{r} \Gamma(1-xr)}} \right)} - 4m_{2}} \times \exp\left(i\left(kx + \frac{(\gamma^{2}m_{1}-k^{2})(1-x)t^{-r}}{2B(x)\sum_{r=0}^{\infty} \left(-\frac{x}{1-x}\right)^{r} \Gamma(1-xr)}} \right)\right),$$

$$n_{5}(x,t) = \frac{16\gamma^{2}m_{1}m_{2}e}{e^{2\sqrt{m_{1}}} \left( \sum_{\substack{\gamma x + \frac{\beta(1-x)t^{-r}}{B(x)\sum_{r=0}^{\infty} \left(-\frac{x}{1-x}\right)^{r} \Gamma(1-xr)}} \right)} - 4m_{2}}}{\left( \frac{2\sqrt{m_{1}} \left( \sum_{\substack{\gamma x + \frac{\beta(1-x)t^{-r}}{B(x)\sum_{r=0}^{\infty} \left(-\frac{x}{1-x}\right)^{r} \Gamma(1-xr)}} \right)} - 4m_{2}} \right)^{2}}.$$
(35)

**Case. II**: When  $m_1 < 0$ , the solution can take the following form





**(a)** 





(b)

**Fig. 1. (a)** The graphs of the modulus of the bright solitons of  $E_1^+$ (**b**) The two and three-dimensional graphs of the modulus of the bright solitons of  $n_1$  at t = 1 respectively, when  $\gamma = 1, \beta = 1.5, m_1 = 2, k = 0.5$ , and  $\alpha = 0.95$ .

$$E_{6}^{\pm}(x,t) = \pm \sqrt{\frac{m_{1}\gamma^{2}(k^{2}-1)}{\cos\left(2\sqrt{-m_{1}}\left(\gamma x - \frac{\beta(x-1)t^{-r}}{B(x)\sum_{r=0}^{\infty}\left(-\frac{\pi}{1-x}\right)^{r}\Gamma(1-xr)}\right)\right)^{-1}} \times \exp\left(i\left(kx + \frac{(\gamma^{2}m_{1}-k^{2})(1-x)t^{-r}}{2B(x)\sum_{r=0}^{\infty}\left(-\frac{\pi}{1-x}\right)^{r}\Gamma(1-xr)}\right)\right),$$

$$n_{6}(x,t) = \frac{2m_{1}\gamma^{2}}{\cos\left(2\sqrt{-m_{1}}\left(\gamma x + \frac{\beta(1-x)t^{-r}}{B(x)\sum_{r=0}^{\infty}\left(-\frac{\pi}{1-x}\right)^{r}\Gamma(1-xr)}\right)\right)^{-1}},$$
(36)





**Fig. 2.** (a) The graphs of the modulus of the bright solitons of  $E_6^+$ (b) The two and three-dimensional graphs of the modulus of the bright solitons of  $n_6$  at t = 1 respectively, when  $\gamma = 1$ ,  $\beta = 1$ ,  $m_1 = -2$ , k = 2, and  $\alpha = 0.9$ .

Considering  $\varepsilon = 1$  the results given above. One may reach the remaining other results for  $\varepsilon = -1$  by utilizing Eqs. (8)-(21).

In the next section, the graphical representation for the solutions for different cases are provided.

#### 4. Results

In this section, we present the plots based on two and threedimensions to present some of the revealed outcomes. The acquired solutions are given by (Figs. 1 and 2).

#### 5. Conclusion

In this work, we have derived hyperbolic and trigonometric exact wave solutions for the ISALWs system of AB fractionalorder using the NAEM. From our solutions obtained in this letter, we conclude that the NAEM is a convenient, efficient, and powerful method for NLFNEEs. Moreover, the results of the proposed NLFNEE in this paper possess many potential usages in engineering and physics. To the best of our knowledge, the solutions revealed for the AB fractional system of equations for the ISALWs are new and have not been submitted to the literature.

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The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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